

# Functional Data Analysis for Generalized Quantile Regression

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## Generalized Quantile Regression (GQR)

- Quantiles and Expectiles are generalized quantiles, Jones (1994).
- Capture the tail behaviour of conditional distributions.
- Applications in finance, weather, demography, ...
- Some applications involve MANY GQR curves.



# Data

High dimensional and complex data in space and time

- Weather: temperature, rainfall, solar activity
- Electricity: futures and options with different time to maturity
- Medicine: gene expression data



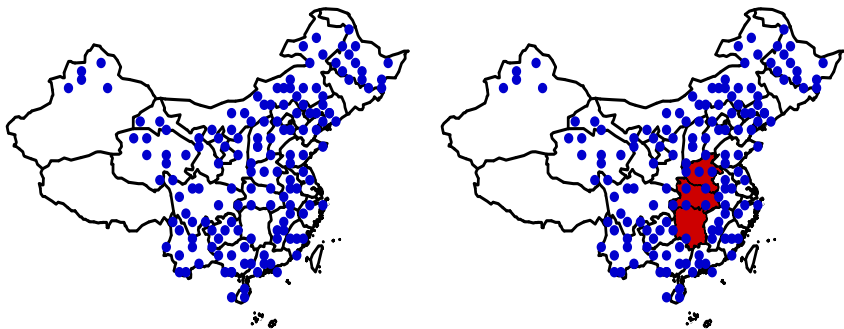


Figure 1: Weather Stations in China



## Statistical Challenges

- ▣ Traditional: estimate GQR individually
- ▣ Directly: estimate GQR jointly
- ▣ common structure neglected
- ▣ too many parameters, curse of dimensionality



## Functional Data Analysis (FDA)

- a tool to capture random curves
- consider dependencies between individuals
- FPCA a tool to reduce dimensionality
- interpretation of factors
- apply "FPCA" and least asymmetric weighted squares (LAWS)





Figure 2: Estimated 95% expectile curves for the volatility of temperature of 30 cities in Germany from 1995-2007.

▶ [Go to details](#)

FDA for GQR





## Weather Derivatives

Temperature indices: Cumulative Averages (CAT) over  $[\tau_1, \tau_2]$ :

$$CAT(\tau_1, \tau_2) = \int_{\tau_1}^{\tau_2} T_u du,$$

where  $T_u = (T_{u,max} + T_{u,min})/2$ .

A CAT temperature future under the non-arbitrage pricing setting:

$$\begin{aligned} F_{CAT}(t, \tau_1, \tau_2) &= E^{Q_\lambda} \left[ \int_{\tau_1}^{\tau_2} T_u du | \mathcal{F}_t \right] \\ &= \int_{\tau_1}^{\tau_2} \Lambda_u du + \mathbf{a}_{t, \tau_1, \tau_2} \mathbf{X}_t + \int_t^{\tau_1} \lambda_u \sigma_u \mathbf{a}_{t, \tau_1, \tau_2} \mathbf{e}_L du \\ &\quad + \int_{\tau_1}^{\tau_2} \lambda_u \sigma_u \mathbf{e}_1^\top \mathbf{A}^{-1} [\exp \{ \mathbf{A}(\tau_2 - u) \} - I_L] \mathbf{e}_L du \quad (1) \end{aligned}$$



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# Outline

1. Motivation ✓
2. Generalized Quantile Estimation
3. FDA for GQR
4. Simulation
5. Application
6. Conclusion



## Quantile and Expectile

Quantile

$$F(l) = \int_{-\infty}^l dF(y) = \tau$$

$$l = F^{-1}(\tau)$$

Expectile

$$G(l) = \frac{\int_{-\infty}^l |y - l| dF(y)}{\int_{-\infty}^{\infty} |y - l| dF(y)} = \tau$$

$$l = G^{-1}(\tau)$$



## Loss Function

Loss function:

$$L(y, \theta) = |y - \theta|^\alpha \quad (2)$$

Asymmetric loss function for generalized quantiles:

$$\rho_\tau(u) = |\mathbf{1}(u \leq 0) - \tau| |u|^\alpha, \quad \tau \in (0, 1) \quad (3)$$

with  $\alpha \in \{1, 2\}$  and  $u = y - \theta$ .



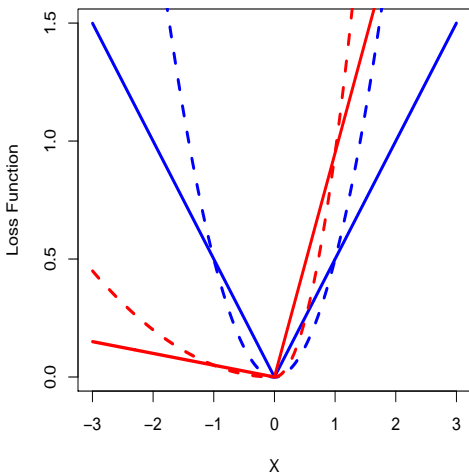


Figure 3: Loss functions for  $\tau = 0.9$  (red);  $\tau = 0.5$  (blue);  $\alpha = 1$  (solid line);  $\alpha = 2$  (dashed line).



## Weight

$$w_\alpha(u) = |\mathbf{I}(u \leq 0) - \tau| |u|^{\alpha-2} \quad (4)$$

Minimum contrast approach:

$$\begin{aligned} l_\tau &= \arg \min_{\theta} E\{\rho_\tau(Y - \theta)\} \\ &= \arg \min_{\theta} E w_\alpha(Y - \theta) |Y - \theta|^2 \end{aligned}$$

Generalized quantile regression curve:

$$\begin{aligned} l_\tau(t) &= \arg \min_{\theta} E\{\rho_\tau(Y - \theta) | X = t\} \\ &= \arg \min_{\theta} E\{w_\alpha(Y - \theta) |Y - \theta|^2 | X = t\} \end{aligned}$$



## Estimation Method

- Kernel Smoothing
  - ▶ Quantile: Fan et.al (1994)
  - ▶ Expectile: Zhang (1994)
- Penalized Spline Smoothing
  - ▶ Quantile: Koenker et.al (1994)
  - ▶ Expectile: Schnabel and Eilers (2009)

GQR can be estimated by LAWS.



## Single Curve Estimation

Rewrite as regression pb:

$$Y_t = I(t) + \varepsilon_t \quad (5)$$

where  $F_{\varepsilon|t}^{-1}(\tau) = 0$ .

Approximate  $I(\cdot)$  by a B-spline basis:

$$I(t) = b(t)^\top \theta_\mu \quad (6)$$

where  $b(t) = \{b_1(t), \dots, b_q(t)\}^\top$  is a vector of cubic B-spline basis and  $\theta_\mu$  is a vector with dimension  $q$ .





## Estimation

Employ a roughness penalty:

$$S(\theta_\mu) = \sum_{t=1}^T w_t (Y_t - b(t)^\top \theta_\mu) \{Y_t - b(t)^\top \theta_\mu\}^2 + \lambda \{ \theta_\mu^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_\mu \} \quad (7)$$

where  $Y = (Y_1, Y_2, \dots, Y_T)^\top$ ,  $\ddot{b}(t) = \frac{\partial^2 b(t)}{\partial t^2}$  and  $w_t = w_\alpha \{Y_t - l(t)\}$  ( $l(t)$  known).



## Estimation

The generalized quantile curve:

$$\begin{aligned}\hat{\theta}_\mu &= \arg \min_{\theta_\mu} S(\theta_\mu) \\ &= \{B^\top W B + \lambda \int \ddot{b}(t) \ddot{b}(t)^\top dt\}^{-1} (B^\top W Y)\end{aligned}$$

$B = \{b(t)\}_{t=1}^T$  is the spline basis matrix with dimension  $T \times q$ , and  $W = \text{diag}\{w_t\}$  defined in (4):

$$\hat{l}(t) = b(t) \hat{\theta}_\mu \tag{8}$$



## Regression Model

$$Y_{ij} = I_i(t_{ij}) + \varepsilon_{ij} \quad (9)$$

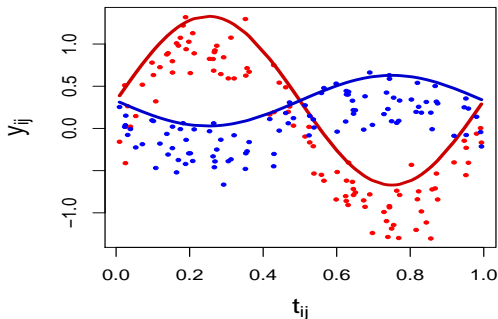


Figure 4: Data design with  $\tau = 0.95$ .  design



## Mixed effect Model

Observe  $i = 1, \dots, N$  individual curves:

$$l_i(t) = \mu(t) + v_i(t) \quad (10)$$

- $\mu(t)$  common shape
- $v_i(t)$  departure from  $\mu(t)$ .

Approximate via

$$l_{ij} = l_i(t_{ij}) = b(t_{ij})^\top \theta_\mu + b(t_{ij})^\top \gamma_{ij} \quad (11)$$

where  $i = 1, \dots, N$  and  $j = 1, \dots, T_i$ .

- Too many parameters to estimate.
- Very volatile for sparse data, James et.al (2000).



## Reduced Model

▸ Mercer's Lemma

▸ Karhunen-Loève Theorem

$$l_i(t) = \mu(t) + \sum_{k=1}^K f_k(t)^\top \alpha_{ik} \quad (12)$$

- ▣  $K$  the number of factors and  $f_k$   $k$ -th factor:

$$f(t) = \{f_1(t), \dots, f_K(t)\}^\top$$

- ▣  $\alpha_i = (\alpha_{i1}, \dots, \alpha_{iK})^\top$  random scores.

Representation of  $\mu$  and  $f$ :

$$\begin{aligned} \mu(t) &= b(t)^\top \theta_\mu \\ f(t)^\top &= b(t)^\top \Theta_f \end{aligned}$$

where  $\theta_\mu \in R^q$  and  $\Theta_f$  with dimension  $q \times K$ .



## Reduced Model

Rewrite (12)

$$l_{ij} = l_i(t_{ij}) = b(t_{ij})^\top \theta_\mu + b(t_{ij})^\top \Theta_f \alpha_i \quad (13)$$

With  $L_i = \{l_i(t_1), \dots, l_i(T_i)\}^\top$ ,  $B_i = \{b(t_1), \dots, b(T_i)\}^\top$ , the GQR curves:

$$L_i = B_i \theta_\mu + B_i \Theta_f \alpha_i \quad (14)$$

Then the model reads:

$$Y_i = L_i + \varepsilon_i = B_i \theta_\mu + B_i \Theta_f \alpha_i + \varepsilon_i \quad (15)$$

with  $Y_i$  is  $T_i \times 1$  and  $\alpha_i$  is  $K \times 1$ .



## Constraints

$$\begin{aligned}\Theta_f^\top \Theta_f &= I_K \\ \int b(t)^\top b(t) dt &= I_q\end{aligned}$$

Orthogonality requirements of the factors:

$$\int f(t) f(t)^\top dt = \Theta_f^\top \int b(t)^\top b(t) dt \Theta_f = I_K$$



## “Empirical” Loss Function

For expectile regression:

$$S = \sum_{i=1}^N \sum_{j=1}^{T_i} w_{ij} \{Y_{ij} - b(t_j)^\top \theta_\mu - b(t_j)^\top \Theta_f \alpha_i\}^2 \quad (16)$$

Roughness penalty:

$$M_\mu = \theta_\mu^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_\mu$$
$$M_f = \sum_{k=1}^K \theta_{kf}^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_{kf}$$

And  $w_{ij} = w_\alpha(Y_{ij} - l_{ij})$ , where  $l_{ij}$  defined in (13).





## LAWS

$$\begin{aligned} S^* &= S + \lambda_\mu M_\mu + \lambda_f M_f \\ &= \sum_{i=1}^N (Y_i - B_i \theta_\mu - B_i \Theta_f \alpha_i)^\top W_i (Y_i - B_i \theta_\mu - B_i \Theta_f \alpha_i) \\ &\quad + \lambda_\mu \left\{ \theta_\mu^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_\mu \right\} \\ &\quad + \lambda_f \left\{ \sum_{k=1}^K \theta_{f,k}^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_{f,k} \right\} \end{aligned} \tag{17}$$

where  $\theta_{f,k}$  is the  $k$ -th column in  $\Theta_f$ .



## Solutions

Minimizing  $S^*$ :

$$\begin{aligned} \hat{\theta}_\mu &= \left\{ \sum_{i=1}^N B_i^\top W_i B_i + \lambda_\mu \int \ddot{b}(t) \ddot{b}(t)^\top dt \right\}^{-1} \\ &\quad \left\{ \sum_{i=1}^N B_i^\top W_i (Y_i - B_i \hat{\Theta}_f \hat{\alpha}_i) \right\} \\ \hat{\theta}_{f,j} &= \left\{ \sum_{i=1}^N \hat{\alpha}_{ij}^2 B_i^\top W_i B_i + \lambda_f \int \ddot{b}(t) \ddot{b}(t)^\top dt \right\}^{-1} \\ &\quad \left\{ \sum_{i=1}^N \hat{\alpha}_{ij} B_i^\top W_i (Y_i - B_i \hat{\theta}_\mu - B_i Q_{ij}) \right\} \end{aligned} \quad (18)$$



$$\hat{\alpha}_i = \left\{ \hat{\Theta}_f^\top B_i^\top W_i B_i \hat{\Theta}_f \right\}^{-1} \left\{ \hat{\Theta}_f^\top B_i^\top W_i (Y_i - B_i \hat{\theta}_\mu) \right\} \quad (19)$$

Where

$$Q_{ij} = \sum_{k \neq j} \hat{\theta}_{f,k} \hat{\alpha}_{ik}$$

and  $i = 1, \dots, N, j = 1, \dots, K$ .

□ initial values

▸ Details

□ updated procedure

▸ Details



## Auxiliary Parameters

- Number of knots is not crucial, James et.al (2000)
- Use 5-fold cross validation (CV) to choose the number of factors and the penalty parameters

$$CV(K, \lambda_\mu, \lambda_f) = \frac{1}{5} \sum_{i=N-(m-1) \times 5}^{N-m \times 5} \sum_{j=1}^{T_i} \hat{w}_{ij} |Y_{ij} - \hat{l}_{ij}|^2 \quad (20)$$

where  $m = 1, 2, \dots, [N/5]$  and  $\hat{w}_{ij} = w_\alpha(Y_{ij} - \hat{l}_{ij})$ .



## Simulation

$$Y_{ij} = \mu(t_j) + f_1(t_j)\alpha_{1i} + f_2(t_j)\alpha_{2i} + e_{ij} \quad (21)$$

with  $i = 1, \dots, N$ ,  $j = 1, \dots, T_i$  and  $t_j$  is equal distanced on  $[0, 1]$ .

The common shape curve and factor functions:

$$\mu(t) = 1 + t + \exp\{-(t - 0.6)^2/0.05\}$$

$$f_1(t) = \sin(2\pi t)/\sqrt{0.5}$$

$$f_2(t) = \cos(2\pi t)/\sqrt{0.5}$$

where  $\alpha_{1i} \sim N(0, 36)$ ,  $\alpha_{2i} \sim N(0, 9)$ .



## Scenarios

- ▣  $e_{ij} \sim N(0, 0.5)$
- ▣  $e_{ij} \sim N(0, \mu(t) \times 0.5)$
- ▣  $e_{ij} \sim t(5)$
  
- ▣ small sample:  $N = 20, T = T_i = 100$
- ▣ large sample:  $N = 40, T = T_i = 150$

Theoretical  $\tau$  quantile and expectile for individual  $i$ :

$$l_{it} = \mu(t) + f_1(t)\alpha_{1i} + f_2(t)\alpha_{2i} + \varepsilon_\tau$$

where  $\varepsilon_\tau$  represents the corresponding theoretical  $\tau$ -th quantile and expectile of the distribution of  $e_{ij}$ .



## Estimators

- The individual curve:

$$l_i = \mu + \sum_{k=1}^K f_k \alpha_{ik}$$

$$\hat{l}_{i,fp} = B_i \hat{\theta}_\mu + B_i \hat{\Theta}_f \hat{\alpha}_i$$

$$\hat{l}_{i,in} : \text{Single curve, see (8)}$$

- The mean curve:

$$m = \mu(t) + e_\tau$$

$$m_{fp} = \frac{1}{N} \sum_{i=1}^N B_i \hat{\theta}_\mu$$

$$m_{in} = \frac{1}{N} \sum_{i=1}^N \hat{l}_{i,in}$$

(22)



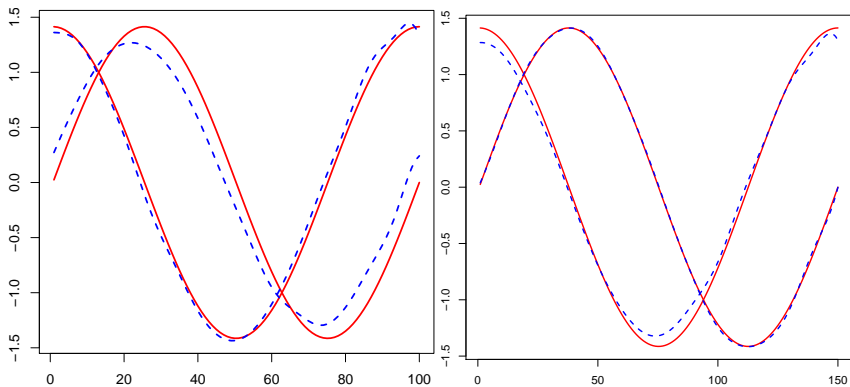


Figure 5: The estimated factors (dashed blue) compared with the true ones (solid red) for the 95% expectile with the error term normally distributed. The left part is for  $N = 20, T = 100$ . The right one is for  $N = 40, T = 150$ .





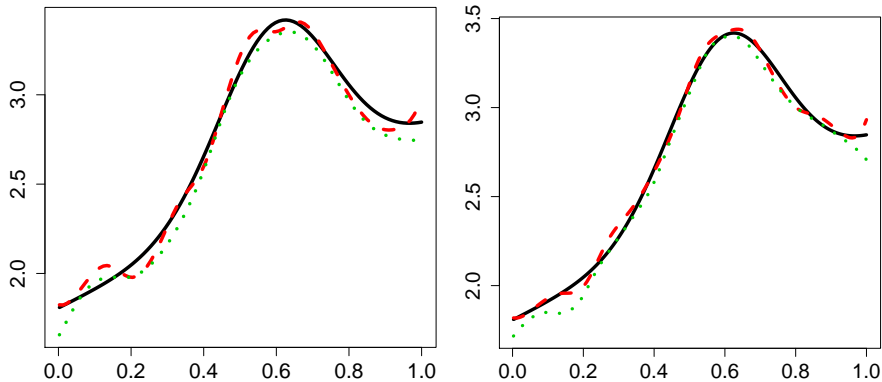


Figure 6: The estimated common shape compared with the true mean for the 95% expectile with the error term normally distributed. The left part is for  $N = 20, T = 100$ . The right one is for  $N = 40, T = 150$ .



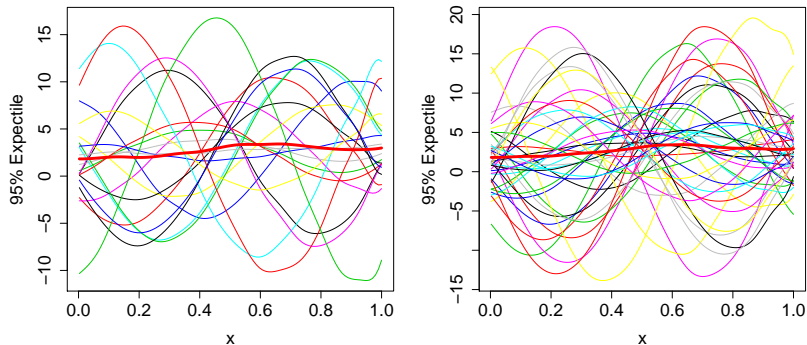


Figure 7: The estimated 95% expectile curves. The thick red line is the common mean curve with the error term normally distributed. The left part is for  $N = 20, T = 100$ . The right one is for  $N = 40, T = 150$ .



<i>Sample Size</i>	<i>Individual</i>		<i>Mean</i>	
	<i>FDA</i>	<i>Single</i>	<i>FDA</i>	<i>Single</i>
$N = 20, T = 100$	0.0469	0.0816	0.0072	0.0093
$N = 40, T = 150$	0.0208	0.0709	0.0028	0.0063
$N = 20, T = 100$	0.1571	0.2957	0.0272	0.0377
$N = 40, T = 150$	0.1002	0.2197	0.0118	0.0172
$N = 20, T = 100$	0.2859	0.5194	0.0454	0.0556
$N = 40, T = 150$	0.1531	0.4087	0.0181	0.0242

Table 1: The mean squared errors (MSE) of the FDA and the single curve estimation for expectile curves with error term is normally distributed with mean 0 and variance 0.5 (Top), with variance  $\mu(t) \times 0.5$  (Middle) and  $t(5)$  distribution (Bottom).



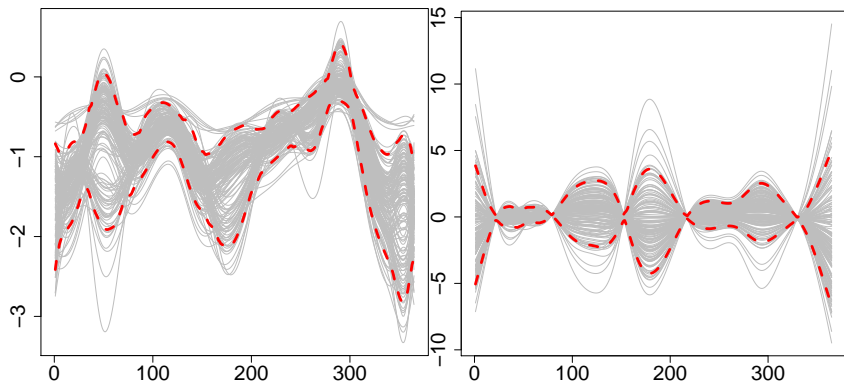


Figure 8: 25% (left) and 50% (right) estimated expectile curves of the temperature variations for 150 weather stations in China in 2010.



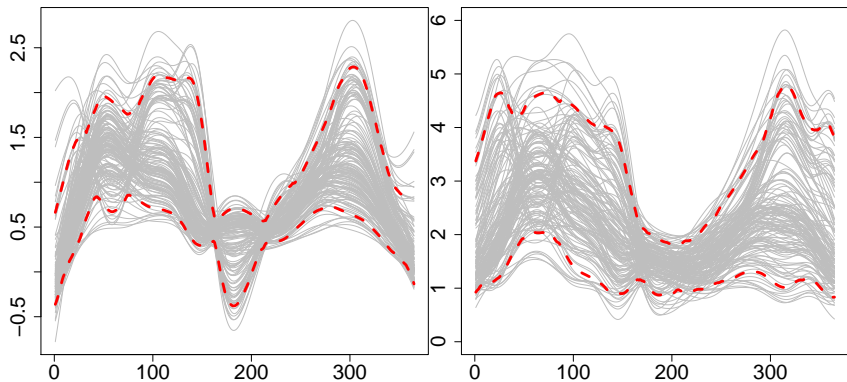


Figure 9: 75% (left) and 95% (right) estimated expectile curves of the temperature variations for 150 weather stations in China in 2010.



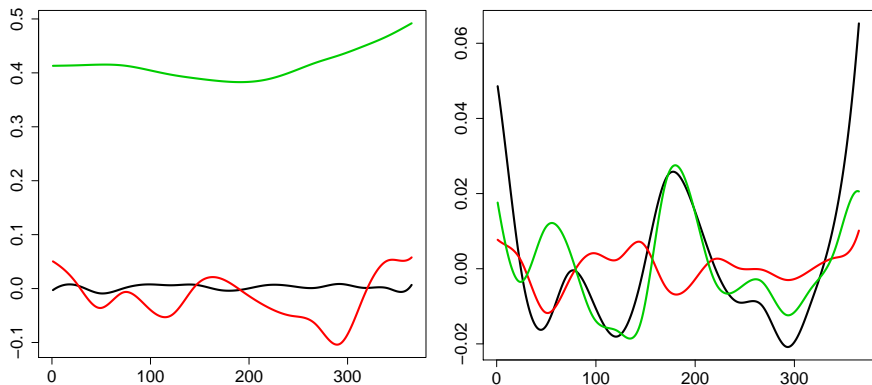


Figure 10: The estimated three factors for 25% (left) and 50% (right) expectile curves of the temperature variation. The black one is the first eigenfunction, the red one is the second and the green one represents the third factor.



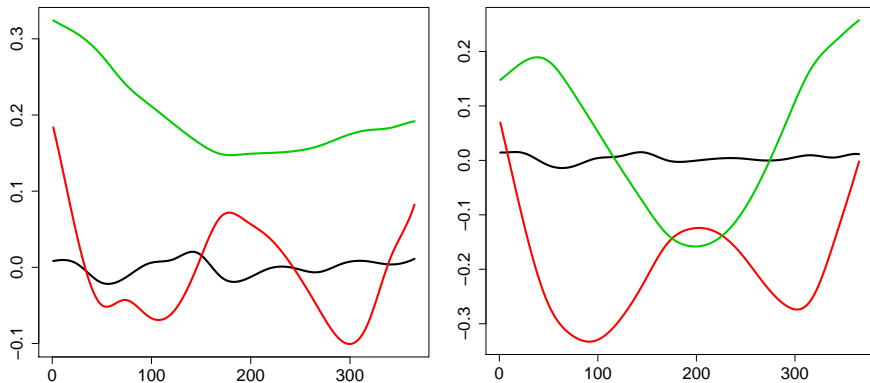


Figure 11: The estimated three factors for 75% (left) and 95% (right) expectile curves of the temperature variation. The black one is the first factor  $f_1$ , the red one is the second  $f_2$  and the green one represents the third factor  $f_3$ .



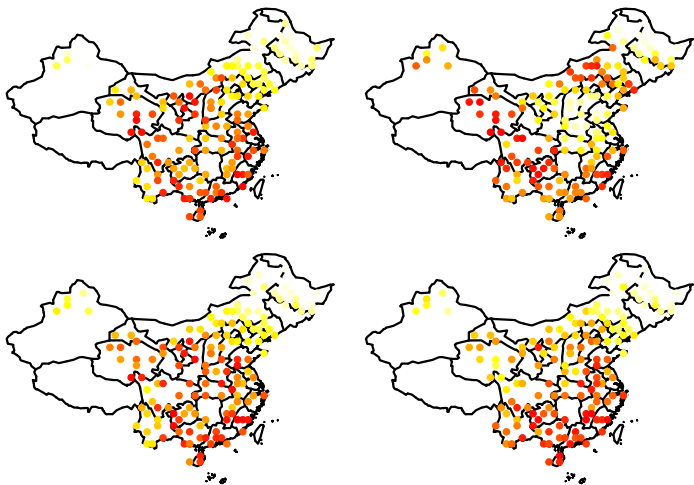


Figure 12: The estimated first random scores  $\alpha_1$  for 25%, 50%, 75% and 95% expectile curves of the temperature variation.





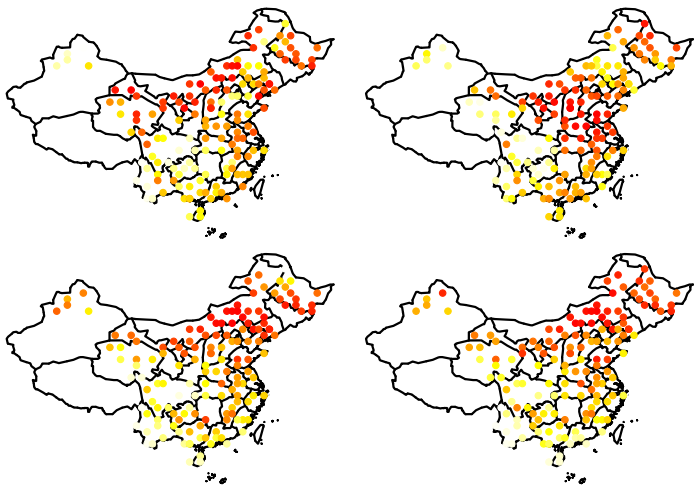


Figure 13: The estimated second random scores  $\alpha_2$  for 25%, 50%, 75% and 95% expectile curves of the temperature variation.



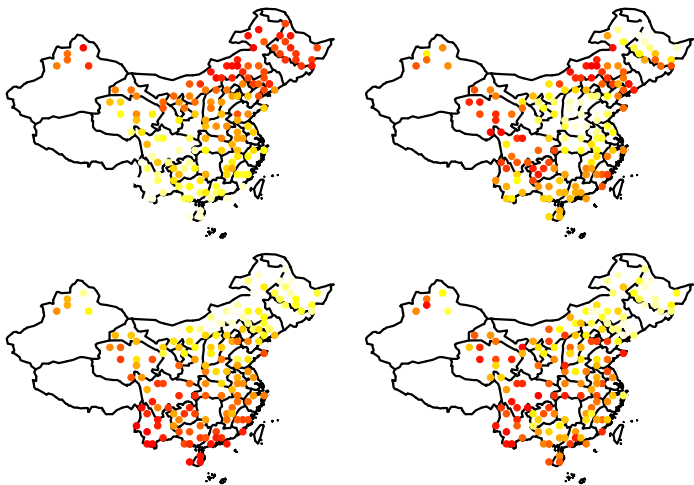


Figure 14: The estimated third random scores  $\alpha_3$  for 25%, 50%, 75% and 95% expectile curves of the temperature variation.



	<i>Min</i>	<i>Max</i>	<i>Median</i>	<i>Mean</i>	<i>SD</i>
$\tau = 0.25$	-68.48	168.30	-14.09	0.00	46.27
$\tau = 0.5$	-129.50	199.50	-18.02	0.00	52.00
$\tau = 0.75$	-22.64	61.20	-8.86	0.00	19.94
$\tau = 0.95$	-60.93	142.60	-12.64	0.00	44.56

Table 2: Statistical Summary of  $\alpha_1$ 

## Conclusion

- Dimension Reduction technique applied to a nonlinear object.
- Provides a novel way to estimate several generalized quantile curves simultaneously.
- Outperforms the single curve estimation, especially when the data is very volatile.
- Pricing weather derivatives more precisely can be possible.



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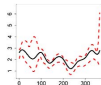
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## Volatility of Temperature

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- The temperature  $T_{it}$  on day  $t$  for city  $i$ :

$$T_{it} = X_{it} + \Lambda_{it}$$

- The seasonal effect  $\Lambda_{it}$ :

$$\Lambda_{it} = a_i + b_i t + \sum_{m=1}^M c_{im} \cos\left\{\frac{2\pi(t - d_{im})}{365}\right\}$$

- $X_{it}$  follows an  $AR(p_i)$  process:

$$X_{it} = \sum_{j=1}^{p_i} \beta_{ij} X_{i,t-j} + \varepsilon_{it} \quad (23)$$

$$\hat{\varepsilon}_{it} = X_{it} - \sum_{j=1}^{p_i} \hat{\beta}_{ij} X_{i,t-j}$$





## Initial Values

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1. Estimate  $N$  single curves  $\hat{l}_i$  individually.
2. Linear regression for  $\hat{\theta}_{\mu 0}$ :  $\hat{l}_i = B_i \theta_{\mu} + \varepsilon_i$
3. Calculate  $\tilde{l}_{i0} = \hat{l}_i - B_i \hat{\theta}_{\mu 0}$ , and  $\hat{\Gamma}_0 = (\hat{\Gamma}_{10}, \dots, \hat{\Gamma}_{N0})$ .

$$\tilde{l}_{i0} = B_i \Gamma_i + \varepsilon_i$$

4. Apply SVD to decompose  $\hat{\Gamma}_{i0}$ :

$$\hat{\Gamma}_{i0} = U D V^T = \Theta_{f0} \alpha_{i0}$$

5. Choose the first  $K$  factors from  $U$  as  $\hat{\Theta}_{f0}$ , and regress  $\hat{\Gamma}_{i0}$  on  $\hat{\Theta}_{f0}$  to get  $\hat{\alpha}_{i0}$ :

$$\hat{\Gamma}_{i0} = \hat{\Theta}_{f0}(\alpha_{i1}, \dots, \alpha_{iK}) + \varepsilon_i \quad (24)$$



## Update Procedure

[Return](#)

1. Plug  $\hat{\Theta}_{f_0}$  and  $\hat{\alpha}_{i_0}$  into (18) to update  $\theta_\mu$ , and get  $\hat{\theta}_{\mu 1}$ .
2. Plugging  $\hat{\theta}_{\mu 1}$  and  $\hat{\alpha}_{i_0}$  into the second equation of (18) gives  $\hat{\Theta}_{f_1}$ .
3. Given  $\hat{\theta}_{\mu 1}$  and  $\hat{\Theta}_{f_1}$ , estimate  $\hat{\alpha}_i$ .
4. Recalculate the weight matrix:

$$w'_{ij} = \begin{cases} \tau & \text{if } Y_{ij} > \hat{l}_{ij} \\ 1 - \tau & \text{if } Y_{ij} \leq \hat{l}_{ij} \end{cases}$$

where  $\hat{l}_{ij}$  is the  $j$ -th element in  $\hat{l}_i = B_i \hat{\theta}_{\mu 1} + B_i \hat{\Theta}_{f_1} \hat{\alpha}_i$

5. Repeat step (1) to (4) until the solutions converge.



## Mercer's Lemma

The covariance operator  $K$

$$K(s, t) = \text{Cov}\{I(s), I(t)\}, E\{I(t)\} = \mu(t), s, t \in \mathcal{T} \quad (25)$$

There exists an orthonormal sequence  $(\psi_j)$  and non-increasing and non-negative sequence  $(\kappa_j)$ ,

$$\begin{aligned}(K\psi_j)(s) &= \kappa_j\psi_j(s) \\ K(s, t) &= \sum_{j=1}^{\infty} \kappa_j\psi_j(s)\psi_j(t) \\ \sum_{j=1}^{\infty} \kappa_j &= \int_{\mathcal{I}} K(t, t)dt < \infty\end{aligned} \quad (26)$$

▶ Return



## Karhunen-Loève Theorem

Under assumptions of Mercer's lemma

$$l(t) = \mu(t) + \sum_{j=1}^{\infty} \sqrt{\kappa_j} \xi_j \psi_j(t) \quad (27)$$

where  $\xi_j := \frac{1}{\sqrt{\kappa_j}} \int l(t) \psi_j(s) ds$ , and  $E(\xi_j) = 0$

$$E(\xi_j \xi_k) = \delta_{j,k} \quad j, k \in \mathbb{N}$$

and  $\delta_{j,k}$  is the Kronecker delta.

▶ Return

