

SONIC: Social Networks with Influencers and Communities

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Analysis of networks

- Social network produces high-dimensional time series
 - ▶ Daily sentiment as quantification of one's opinion
 - ▶ Missing observations
- Adjacency matrix must be estimated
- Problem: network size is immense
- Smart data analytics based on StockTwits



StockTwits sentiment

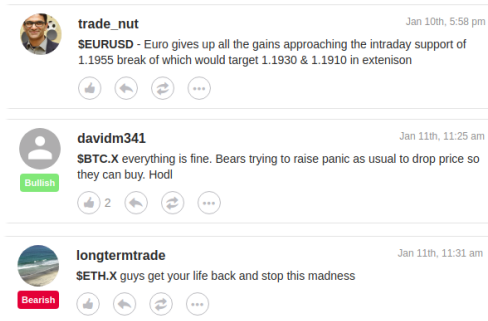


Figure 1: <https://www.stocktwits.com> message examples



Sentiment weight: $tf \cdot idf$ scheme

the
brown
cow

For each term t ,

$$SW(t) = \frac{tf \cdot idf_{pos}(t) - tf \cdot idf_{neg}(t)}{tf \cdot idf_{pos}(t) + tf \cdot idf_{neg}(t)}$$





where

$$tf \cdot idf_{pos}(t) = freq_{pos}(t) \cdot \log \frac{\text{positive messages}}{\text{positive occurrences of } t}$$

$$tf \cdot idf_{neg}(t) = freq_{neg}(t) \cdot \log \frac{\text{negative messages}}{\text{negative occurrences of } t}$$



Crypto-specific terms

Term	Sentiment weight
	0.90
	-0.91
	-0.98
hodl	0.32
hodl !	0.64
hackers	-0.83
miner	0.62
tulip mania	-0.94
bitcoin 	-0.73
scam	-0.77
f***ing scam	-0.86

CYH Chen
Dictionary



@AAPL

[► Numbers](#)

Figure 2: SWs constructed from @AAPL messages



@BTC

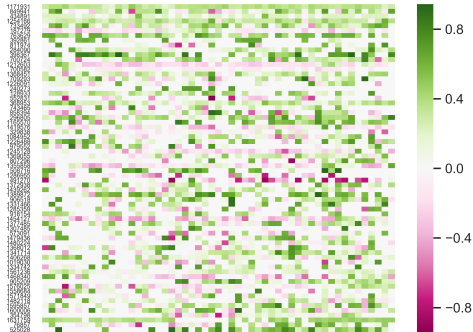


Figure 3: SWs constructed from @BTC messages



Modeling opinion networks

- Sentiment weights (SW) for N users during T days

Z_{it} = average of SWs for user i during day t

$$Z_t \in \mathbb{R}^N$$

- Missing observations

$$Z_{it} = \delta_{it} Y_{it}, \quad \text{i.i.d. } \delta_{it} \sim \text{Bernoulli}(p_i)$$

where Y_{it} is the *opinion*, Z_{it} — *expressed opinion*



Modeling opinion networks

- Network interactions through VAR

$$Y_t = \Theta Y_{t-1} + W_t, \quad E[W_t | \mathcal{F}_{t-1}] = 0, \\ \Theta \in \mathbb{R}^{N \times N},$$

- ▶ Unknown adjacency matrix
- ▶ Curse of dimensionality $T \lesssim N$



Zhu, X., Pan, R., Li, G., Liu, Y. and Wang, H.

Network vector autoregression

Annals of Statistics, 2017

▶ more Literature

$$\Theta_{ij} = \beta A_{ij} / \sum_k A_{ik}, \text{ known } A!$$



Influencer

- ▣ Relationships expressed by VAR parameters

$$\Theta_{ij} \neq 0 \Rightarrow i \text{ follows } j$$

- ▣ Influencer — followed by a significant part of network
- ▣ The amount of influencers is much smaller than N
 - ▶ motivated by real life social networks
 - ▶ sparsity constraints reduce sample complexity



Research question

- Each user is affected at most by s others

$$\max_i \sum_j \mathbf{1}(\Theta_{ij} \neq 0) \leq s;$$

- Sparsity grows up to $\|\Theta\|_0 \leq Ns$, so lasso requires

$$\frac{(sN) \log N}{T} \ll 1$$

$$(\|\Theta\|_0 = \sum_{ij} \mathbf{1}(\Theta_{ij} \neq 0))$$

- Structural assumptions appropriate for social networks?*



Outline

1. Motivation ✓
2. New structural approach
3. Estimation
4. Missing observations
5. Local result
6. Simulations
7. StockTwits analysis
8. Outlook



Stochastic Block Model

- Partition of nodes into K disjoint *communities*

$$C_1 \cup \dots \cup C_K = \{1, \dots, N\}, \quad C_i \cap C_j = \emptyset$$

- Independent edges $P(a_{ij} = 1) = \Omega_{ij}$ with

$$\Omega_{ij} = B_{l_i l_j}, \quad \text{for } i \in C_{l_i}, j \in C_{l_j}$$

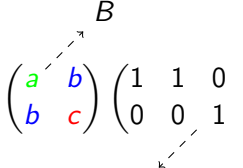
(usually arbitrary diagonal elements Ω_{ii} allowed)

- Low rank assumption: $\text{Rank}(\Omega) \leq K$



□ Example for $N = 5$, $K = 2$

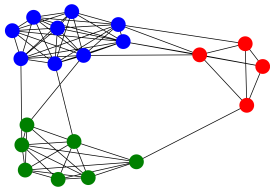
$$\Omega = \begin{pmatrix} a & a & b & b & b \\ a & a & b & b & b \\ b & b & c & c & c \\ b & b & c & c & c \\ b & b & c & c & c \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 \end{pmatrix}$$

B

 index matrix



Realization for $N = 20$, $K = 3$

$$\Omega = \begin{pmatrix} \begin{array}{|c|c|c|} \hline \text{1.0} & & \\ \hline \end{array} & \begin{array}{|c|c|} \hline \text{0.1} & \\ \hline \end{array} & \begin{array}{|c|c|} \hline \text{0.05} & \\ \hline \end{array} \\ \hline \begin{array}{|c|c|c|} \hline \text{0.1} & \text{0.9} & \\ \hline \end{array} & \begin{array}{|c|c|} \hline \text{0.05} & \\ \hline \end{array} & \begin{array}{|c|c|} \hline \text{0.05} & \\ \hline \end{array} \\ \hline \begin{array}{|c|c|c|} \hline \text{0.05} & & \\ \hline \end{array} & \begin{array}{|c|c|} \hline \text{0.05} & \\ \hline \end{array} & \begin{array}{|c|c|} \hline \text{0.95} & \\ \hline \end{array} \\ \hline \end{pmatrix}$$



New structural approach

- Few influencers: row-wise sparsity

$$\max_i \sum_j \mathbf{1}(\Theta_{ij} \neq 0) \leq s$$

- Communities C_1, \dots, C_K with shared dependencies

$$\Theta_{i\cdot} = \Theta_{i'\cdot}, \quad i, i' \in C_l$$

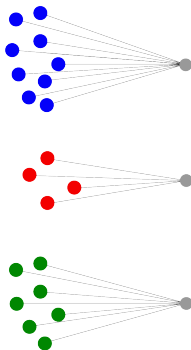


Chen, Y., Trimborn, S., Zhang, J.

Discover Regional and Size Effects in Global Bitcoin Blockchain via Sparse-Group Network AutoRegressive Modeling
preprint, 2018



Influencers and communities



$$\Theta = \begin{pmatrix} \begin{array}{|c|} \hline \text{Blue bar} \\ \hline \end{array} \\ \hline \begin{array}{|c|} \hline \text{Pink bar} \\ \hline \end{array} \\ \hline \begin{array}{|c|} \hline \text{Green bar} \\ \hline \end{array} \end{pmatrix}$$



Clustering

- Via user *labels*: $\mathcal{C} = (l_1, \dots, l_N)$, where $l_i \in [K]$

$$C_l = \{i : l_i = l\}$$

- Relabeling $\mathcal{C} \sim \mathcal{C}'$ iff there is π

$$l_i = \pi(l'_i), \quad i = 1, \dots, N$$

- *Equivalent* distance,

$$\begin{aligned} d(\mathcal{C}, \mathcal{C}') &= \min_{\pi} \sum_{i=1}^N \mathbf{1}(l_i \neq \pi(l'_i)) \\ &= \min_{\pi} \sum_{j=1}^K |C_j \setminus C'_{\pi(j)}| \end{aligned}$$

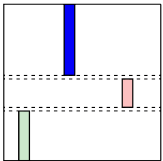


Block structure

- Shared dependencies in each community

$$l_i = l_{i'} \Rightarrow \Theta_{ij} = \Theta_{i'j}, \quad j = 1, \dots, N$$

- Example $K = 3$

$$\Theta = \left(\begin{array}{|c|} \hline \text{[Diagram of a 3x3 matrix with colored blocks]} \\ \hline \end{array} \right)$$



(up to a permutation)



Block structure 2

- Each column of Θ is a span of

$$z_{C_j} = \frac{1}{\sqrt{|C_j|}} \begin{pmatrix} 0 \\ 0 \\ \boxed{1} \\ \vdots \\ \boxed{1} \\ 0 \end{pmatrix} \quad j = 1, \dots, K$$

 C_j

- Factor representation

$$\Theta = Z_C V^T, \quad V \in \mathbb{R}^{N \times K}$$

where $Z_C = [z_{C_1}, z_{C_2}, \dots, z_{C_K}]$



Influencers and sparsity

- In social media users are influenced by a small group of people (e.g. celebrities)

user j is **influencer** iff $\Theta_{ij} \neq 0$ for some i

- Induce row-wise sparsity on $\Theta = Z_C V^\top$, i.e.

$$\max_j \sum_{i=1}^N \mathbf{1}(V_{ij} \neq 0) \leq s$$

- Sparsity + clusterisation = dimensionality reduction



Penalized loss function

- Define

$$R_\lambda(V; \mathcal{C}) = \frac{1}{2} \sum_{t=2}^T \|Y_{t+1} - Z_{\mathcal{C}} V^\top Y_t\|^2 + \lambda \|V\|_{1,1}$$

- ℓ_1 penalty $\|V\|_{1,1} = \sum_{ij} |V_{ij}|$ with a tuning parameter λ
- Minimum contrast estimator

$$(\hat{V}_\lambda, \hat{\mathcal{C}}_\lambda) = \arg \min R_\lambda(V; \mathcal{C}), \quad \hat{\Theta}_\lambda = Z_{\hat{\mathcal{C}}_\lambda} \hat{V}_\lambda^\top$$



LASSO estimator for V

- Penalized risk minimization with a given clustering \mathcal{C}

$$\hat{V}_{\mathcal{C},\lambda} = \arg \min_V R_\lambda(V; \mathcal{C})$$

- Convex problem for V
- Parallelization is possible: K independent subproblems due to $Z_{\mathcal{C}}^\top Z_{\mathcal{C}} = I$

$$\hat{v}_j = \arg \min_{v \in \mathbb{R}^\top} \frac{1}{2} \sum_{t=1}^{T-1} \left\{ (z_{C_j}^\top Y_{t+1}) - v^\top Y_t \right\}^2 + \lambda \|v\|_1$$



Greedy procedure

Minimize the risk for clustering

$$F_{\lambda}(\mathcal{C}) = \min_V R_{\lambda}(V; \mathcal{C}) \rightarrow \min_{\mathcal{C}}$$

1. randomly initialize C_1, \dots, C_K ;
2. for each $i = 1, \dots, N$ change the label of the i th user

$$F_{\lambda}(\mathcal{C}) \rightarrow \min_{l_i}$$

(i.e. $d(\mathcal{C}^{old}, \mathcal{C}^{new}) \leq 1$)

3. repeat (2) until clustering does not change;



Alternating procedure

Joint risk



$$R_{\lambda}(V; \mathcal{C}) = \frac{1}{2} \text{Tr}(V^{\top} \hat{\Sigma} V) - \text{Tr}(V^{\top} \hat{A} Z_{\mathcal{C}}) + \lambda \|V\|_{1,1}$$

1. randomly initialize $\mathcal{C} = (C_1, \dots, C_K)$;
2. estimate $\hat{V}_{\mathcal{C}, \lambda}$ using LASSO;
3. repeat:
 - 3.1 perform greedy procedure for

$$-\text{Tr}(\hat{V}^{\top} A Z_{\mathcal{C}}) \rightarrow \min_{\mathcal{C}}$$

- 3.2 update $\hat{V}_{\mathcal{C}, \lambda}$ using the new clustering;
 - 3.3 repeat until does not change



Missing observations

Unobserved “opinion” process

$$Y_t = \Theta^* Y_{t-1} + W_t$$

- true parameter Θ^*
- innovations W_t with $E(W_t | \mathcal{F}_{t-1}) = 0$

Observed variables

$$Z_{it} = \delta_{it} Y_{it}, \quad \delta_{it} \sim \text{Bernoulli}(p_i)$$

- user i makes a post with probability p_i every day
- still allows estimation of the covariance of Y



Loss decomposition

$$\begin{aligned} L(\Theta) &= \frac{1}{2T} \sum_{t>1} \|Y_t - \Theta Y_{t-1}\|_2^2 \\ &= \frac{1}{2} \text{Tr}(\Theta \tilde{\Sigma} \Theta^\top) - \text{Tr}(\Theta \tilde{A}) + \frac{1}{2T} \sum_{t>1} \|Y_t\|^2 \end{aligned}$$

where

$$\tilde{\Sigma} = T^{-1} \sum_{t>1} Y_{t-1} Y_{t-1}^\top, \quad \tilde{A} = T^{-1} \sum_{t>1} Y_{t-1} Y_t^\top$$



Probabilities of non-zero observation

$$\hat{p}_i = T^{-1} \sum_t \mathbf{1}(Z_{it} \neq 0)$$

Observed sample covariance

$$\Sigma^* = T^{-1} \sum_t Z_t Z_t^\top, \quad A^* = T^{-1} \sum_{t>1} Z_{t-1} Z_t^\top$$

Covariance estimation

$$\hat{\Sigma} = \text{diag}(\hat{p})^{-1} \text{Diag}(\Sigma^*) + \text{diag}(\hat{p})^{-1} \text{Off}(\Sigma^*) \text{diag}(\hat{p})^{-1}$$

$$\hat{A} = \text{diag}(\hat{p})^{-1} A^* \text{diag}(\hat{p})^{-1}$$

► Upper bound



Lounici, K.

High-dimensional covariance matrix estimation with missing observations

Bernoulli, 2014



Local result

- Recall the definition

$$d(\mathcal{C}, \mathcal{C}') = \sum_{j=1}^K |\mathcal{C}_j \setminus \mathcal{C}'_j|$$

(1 if only one label differs)

- Greedy algorithm changes one label at each step
- If \mathcal{C} is such that

$$\min_{d(\mathcal{C}, \mathcal{C}')=1} F_{\lambda}(\mathcal{C}') \geq F_{\lambda}(\mathcal{C}),$$

the algorithm stops at \mathcal{C} — “locally optimal”;



Conditions

□ $\Theta^* = Z^*[V^*]^\top$ with $Z^* = Z_{\mathcal{C}^*}$ and

$$V = [v_1^*, \dots, v_K^*], \quad \|v_j^*\|_0 \leq s,$$

where $\|x\|_0 = \sum \mathbf{1}(x_i \neq 0)$;

□ $\|\Theta^*\|_\infty = \|V^*\|_\infty \leq \gamma < 1$;

□ condition number of $[V^*]^\top \Sigma V^*$ bounded by κ_0 ;

□ significant size of clusters

$$\min_j |C_j^*| / \max_j |C_j^*| \geq \alpha \in (0, 1]$$



ERC condition

Denote *exact recovery coefficient* (ERC)

$$\text{ERC}(\Lambda) = 1 - \|\Sigma_{\Lambda^c \Lambda} \Sigma_{\Lambda, \Lambda}^{-1}\|_{1, \infty},$$

where $\|A\|_{1, \infty} = \max_i \sum_j |A_{ij}|$

□ Suppose,

$$\text{ERC}(\Lambda_j) \geq 3/4$$

for each $\Lambda_j = \text{supp}(v_j^*)$



Tropp, J.

Just relax: Convex programming methods for identifying sparse signals in noise

IEEE Transactions on Information Theory, 2006



Network size limits

We work in the regime

$$\frac{s n^* \log N}{T p_{\min}^2} \leq c$$

with $c > 0$ not depending on N, s, K, T, δ_i ;

□ *largest cluster size n^* within the range*

$$\frac{N}{K} \leq n^* \leq \frac{\alpha^{-1} N}{K}$$

□ allows $N > T$ for sufficiently large K



Local result

Theorem

There are constants c, C such that if

□ the tuning parameter satisfies

$$C \sqrt{\frac{\log N}{Tp_{\min}^2}} \leq \lambda \leq c \{s^{-1} \vee (\sqrt{s}K)^{-1}\},$$

□ $N \geq c'\lambda^2 sK$,

then with probability at least $1 - 1/N$ there is a locally optimal \hat{C} such that $\hat{\Theta}_\lambda = Z_{\hat{C}} \hat{V}_{\hat{C}, \lambda}$ satisfies

$$\|\hat{\Theta}_\lambda - \Theta^*\|_F \lesssim \lambda K \sqrt{s}$$

► Proof sketch



Ideally we choose

$$\lambda^* \sim \sqrt{\frac{\log N}{Tp_{\min}^2}}$$

In this case the bound is

$$\|\hat{\Theta}_{\lambda^*} - \Theta^*\|_F \lesssim \sqrt{\frac{sK^2 \log N}{Tp_{\min}^2}}$$



Simulations

- $N = 100, T = 100$
- Construct Θ^* such that
 - ▶ $K = 2..30$ with C_j having equal (± 1) sizes;
 - ▶ for each $j = 1, \dots, K$
 $\text{supp}(v_j^*) = 1;$
 - ▶ $\|\Theta^*\|_{op} = 0.5$

- Simulate

$$Y_t = \sum_{k \geq 0} [\Theta^*]^k W_{t-k}, \quad W_t \sim N(0, I_N)$$



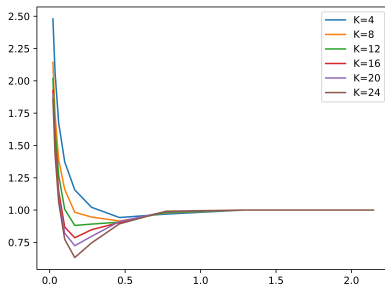


Figure 4: Normalized error $E\|\hat{\Theta}_\lambda - \Theta^*\|_F / \|\Theta^*\|_F$ against λ



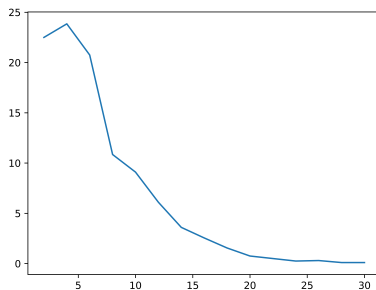


Figure 5: Cluster difference for optimal λ against $K = 2, \dots, 30$



Choice of λ

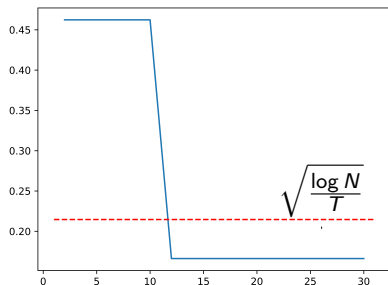


Figure 6: Optimal λ for $K = 2, \dots, 30$

- Best choice appears to be

$$\lambda^* \approx \sigma \sqrt{\frac{\log N}{T p_{\min}^2}};$$

- In case of unknown σ take

$$\hat{\sigma} = \lambda_{K+1}(\hat{\Sigma});$$



Experiment with StockTwits

□ Preprocessing


- ▶ pick users with $\hat{p}_i \geq 0.5$ (small p_i produce too much error)
- ▶ persistence: covariance estimator requires stationarity of (δ_{it})
- ▶ result: 46 users & 72 days

□ Estimation

- ▶ 100 iterations with 100 initializations



@AAPL



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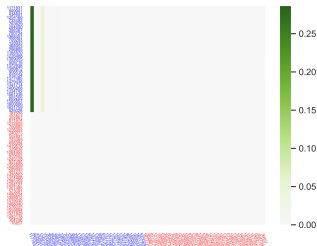


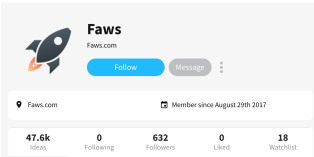
Figure 8: Estimated Θ for BTC daily sentiment

 Opinion_Networks_in_Social_Media

► How to choose K?



@BTC

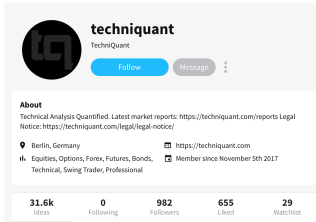


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Cha, M., Haddadi, H., Benevenuto, F., Gummadi, K.P.

Measuring User Influence in Twitter: The Million Follower Fallacy
4th AAAI conference on weblogs and social media, 2010






Outlook

- Network autoregression for social media
- Application to StockTwits sentiment
 - ▶ identify clusters and influencers
- How to verify our model?
 - ▶ follower/followee relationship unavailable in StockTwits
 - ▶ analysis of cluster stability



Literature

-  Zhu, X., Pan, R., Li, G., Liu, Y. and Wang, H.
Network vector autoregression
Annals of Statistics, 2017
-  Chernozhukov, V., Härdle, W.K., Huang, C., Wang, W.
LASSO-driven Inference in Time and Space
preprint, 2018
-  Chen, C.Y.H, Härdle, W, Okhrin, Y.
Tail event driven networks of SIFIs
Journal of Econometrics, 2019
DOI: 10.1016/j.jeconom.2018.09.016



@AAPL

- Sample period: 2017/05/22 to 2019/01/27 (~ 600 days)
- 449,761 messages from 26,521 users
 - ▶ 29.6% bullish / 10.7% bearish / 59.7% unlabelled
 - ▶ training dataset 99,985 positive / 36,100 negative
- Lexicon from @AAPL messages
 - ▶ 543 positive terms
 - ▶ 786 negative terms

[▶ Back](#)



Zhu, X., Wang, W., Wang, H. and Härdle, W.K.

Network quantile autoregression

Journal of Econometrics, 2019



Chernozhukov, V., Härdle, W.K., Huang, C., Wang, W.

LASSO-driven Inference in Time and Space

Ann. Stat., to appear



Chen, C. H.-Y., Härdle, W.K., Liu, K.

Financial Risk Meter

Empirical Economics, to appear



Chen, Y., Trimborn, S., Zhang, J.

Discover Regional and Size Effects in Global Bitcoin Blockchain via Sparse-Group Network AutoRegressive Modeling

preprint, 2018



subgaussian innovations

$$\|\langle u, W_t \rangle\|_{\psi_2} \lesssim \|\langle u, W_t \rangle\|_{L_2}$$

where

$$\|X\|_{\psi_2} = \inf\{C > 0 : E \exp(|X|^2/C) \leq 2\}$$

$$\|X\|_{L_2} = E^{1/2}|X|^2$$



Lemma

Suppose,

- W_t are subgaussian;
- $\|\Theta^*\|_{op} \leq \gamma < 1$;
- $P, Q \in \mathbb{R}^{N \times N}$ are projectors of ranks $\leq M$.

It holds with probability at least $1 - e^{-u}$ for $u \geq 1$

$$\begin{aligned} & \|P(\hat{\Sigma} - \Sigma)Q\|_{op} \\ & \leq C\|\Sigma\|_{op} \left(\sqrt{\frac{M(\log N + u)}{Tp_{\min}^2}} \vee \frac{M(\log N + u) \log T}{Tp_{\min}^2} \right), \end{aligned}$$

where $C = C(\gamma)$



Lemma

Suppose,

- Y_1, \dots, Y_T are subgaussian;
- $\|\Theta^*\|_{op} \leq \gamma < 1$;
- $P, Q \in \mathbb{R}^{N \times N}$ are projectors of ranks $\leq M$.

It holds with probability at least $1 - e^{-u}$ for $u \geq 1$

$$\begin{aligned} & \|P(\hat{A} - A)Q\|_{op} \\ & \leq C\|\Sigma\|_{op} \left(\sqrt{\frac{M(\log N + u)}{Tp_{\min}^2}} \vee \frac{M(\log N + u) \log T}{Tp_{\min}^2} \right), \end{aligned}$$

where $C = C(\gamma)$



Theorem (Chapter 4)

Let $X_1, \dots, X_T \in \mathbb{R}^{d \times d}$ are independent with $\| \|X_i\| \|_{\psi_1} < \infty$. Set

$$\square \quad \sigma^2 = \left\| \mathbb{E} \sum_{i=1}^T X_i^2 \right\|$$

$$\square \quad U = \left\| \max_{i \leq T} \|X_i\| \right\|_{\psi_1}$$

Then for each $t \geq 1$

$$\mathbb{P} \left(\left\| \sum_{i=1}^N X_i - \mathbb{E} X_i \right\| \lesssim \sigma \sqrt{t} + Ut \right) \leq de^{-t}$$

Here $\|Y\|_{\psi_1} = \inf \{ C > 0 : \mathbb{E} \exp(|Y|/C) \leq 2 \}$



How to choose number K?

- Analyze stability of cluster estimation
- Consider few shorter windows (say, of length $\frac{3T}{4}$)

$$\mathcal{I}_1 = \left[0, \frac{3}{4}T\right], \mathcal{I}_2 = \left[\frac{1}{20}T, \left(\frac{3}{4} + \frac{1}{20}\right)T\right], \dots, \mathcal{I}_6 = \left[\frac{1}{4}T, T\right]$$

- Compare resulting clusterings

$$d(\hat{\mathcal{C}}(\mathcal{I}_1), \hat{\mathcal{C}}(\mathcal{I}_j)), \quad j = 2, \dots, 6,$$

where $\hat{\mathcal{C}}(\mathcal{I})$ is estimated using data from time interval \mathcal{I}



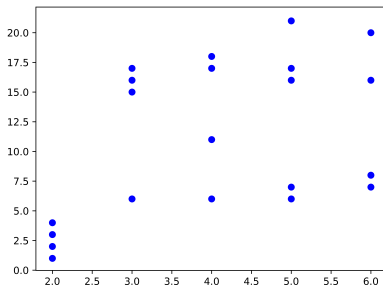


Figure 9: Cluster differences for $K = 2, 3, 4, 5, 6$ for the BTC dataset

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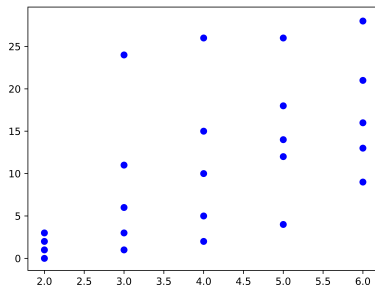


Figure 10: Cluster differences for $K = 2, 3, 4, 5, 6$ for the BTC dataset

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Proof sketch

- Exact recovery $\text{supp}(v_j) = \Lambda_j$ in the neighbourhood of \mathcal{C}^* (w.h.p.);
- Explicit expression for $F_\lambda(\mathcal{C})$;
- Quadratic deviation of deterministic part v.s. linear growth of stochastic part



Gribonval, R., Jenatton, R., Bach, F.

Sparse and spurious: dictionary learning with noise and outliers

IEEE Transactions on Information Theory, 2015

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V-step

For arbitrary $\mathcal{C} = (C_1, \dots, C_K)$ we solve for each $j = 1, \dots, K$

$$\hat{v}_j = \arg \min \frac{1}{2} v^\top \hat{\Sigma} v - v^\top \hat{A} z_j + \lambda \|v\|_1,$$

where $Z_{\mathcal{C}} = [z_1, \dots, z_K]$

Lemma

Denote, $\hat{c} = \hat{A} z_j$. Suppose,

$$\|\hat{\Sigma}_{\Lambda_j^c, \Lambda_j} \hat{\Sigma}_{\Lambda_j, \Lambda_j}^{-1} \hat{c}_{\Lambda_j} - \hat{c}_{\Lambda_j^c}\|_{\infty} \leq \lambda (1 - \|\hat{\Sigma}_{\Lambda_j^c, \Lambda_j} \hat{\Sigma}_{\Lambda_j, \Lambda_j}^{-1}\|_{1, \infty})$$

where $\|A\|_{1, \infty} = \max_i \sum_j |A_{ij}|$. Then, $\text{supp}(\hat{v}_j) \subset \Lambda_j$.



Solution with $\text{supp}(\hat{v}_j) \subset \Lambda_j$

$$\hat{v}_j = \Sigma_{\Lambda_j, \Lambda_j}^{-1} (\hat{A}_{\Lambda_j, \cdot} z_j - \lambda g)$$

with some $g \in \mathbb{R}^{|\Lambda_j|}$, $\|g\|_\infty \leq 1$

If $\|\hat{v}_j - v_j^*\|_\infty < \min_{i \in \Lambda_j} |V_{ij}^*|$ then follows *explicit form*

$$\hat{v}_j = \hat{\Sigma}_{\Lambda_j, \Lambda_j}^{-1} (\hat{A}_{\Lambda_j, \cdot} z_j - \lambda (s_j^*)_{\Lambda_j})$$

where $s_j^* = \text{sign}(v_j^*)$



Exact recovery yields

$$\begin{aligned} F_{\lambda}(\mathcal{C}) &= -\frac{1}{2} \sum_{j=1}^K \hat{\mathbf{v}}_j^{\top} \hat{\Sigma} \hat{\mathbf{v}}_j \\ &= -\frac{1}{2} \sum_{j=1}^K \underbrace{\left(\hat{A}_{\Lambda_j, \cdot} z_j - \lambda(s_j^*)_{\Lambda_j} \right)^{\top} \hat{\Sigma}_{\Lambda_j, \Lambda_j}^{-1} \left(\hat{A}_{\Lambda_j, \cdot} z_j - \lambda(s_j^*)_{\Lambda_j} \right)}_{=\Phi_{\lambda}(\mathcal{C})} \end{aligned}$$



Lemma

Let $\lambda, \bar{r} > 0$ be such that

$$C \sqrt{\frac{\log N}{Tp_{\min}^2}} \leq \lambda \leq c s^{-1}, \quad \sqrt{\frac{n^* \log N}{Tp_{\min}^2}} \bar{r}^2 \leq c \lambda.$$

Then, with probability $\geq 1 - N^{-\beta}$

$$F_{\lambda}(\mathcal{C}) = \Phi_{\lambda}(\mathcal{C}), \quad \forall \mathcal{C} : \|Z_{\mathcal{C}} - Z_{\mathcal{C}^*}\|_{\text{F}} \leq \bar{r}$$

Moreover,

$$\|\hat{V}_{\mathcal{C}, \lambda} - V^*\|_{\text{F}} \lesssim \lambda \sqrt{Ks}$$



Estimation of clusters

Define,

$$\hat{\mathcal{C}} = \arg \min_{\mathcal{C}: \|Z_{\mathcal{C}} - Z_{\mathcal{C}^*}\|_F \leq \bar{r}} \Phi_{\lambda}(\mathcal{C})$$

quadratic vs. (at most) linear for $r = \|Z_{\mathcal{C}} - Z_{\mathcal{C}^*}\|_F \leq \bar{r}$

$$\Phi_{\lambda}(\mathcal{C}) - \Phi_{\lambda}(\mathcal{C}^*) \geq \left(c - C \sqrt{\frac{sn^* \log N}{Tp_{\min}^2}} \right) r^2 - C\lambda\sqrt{s}Kr$$



Define,

$$\bar{\Phi}_{\lambda}(\mathcal{C}) = -\frac{1}{2} \sum_{j=1}^K (A_{\Lambda_j, \cdot} z_j - \lambda(s_j^*)_{\Lambda_j})^{\top} \Sigma_{\Lambda_j, \Lambda_j}^{-1} (A_{\Lambda_j, \cdot} z_j - \lambda(s_j^*)_{\Lambda_j})$$

when $r = \|Z_{\mathcal{C}} - Z_{\mathcal{C}^*}\|_F \leq 0.3$

$$\bar{\Phi}_{\lambda}(\mathcal{C}) - \bar{\Phi}_{\lambda}(\mathcal{C}^*) \geq \frac{a_0 r^2}{4} (1 - 10\alpha^{-1} r^2) - \lambda \sqrt{Ks} \|V^*\|_F r$$



With probability at least $1 - N^{-\beta}$

$$\begin{aligned} & |\Phi_\lambda(\mathcal{C}) - \bar{\Phi}_\lambda(\mathcal{C}) - \Phi_\lambda(\mathcal{C}^*) + \bar{\Phi}_\lambda(\mathcal{C}^*)| \\ & \lesssim \sqrt{\frac{sK \log N}{Tp_{\min}^2}} r + \sqrt{\frac{sn^* \log N}{Tp_{\min}^2}} r^2 \end{aligned}$$



$$\begin{aligned}\Phi_\lambda(\mathcal{C}) - \Phi_\lambda(\mathcal{C}^*) &\geq \bar{\Phi}_\lambda(\mathcal{C}) - \bar{\Phi}_\lambda(\mathcal{C}^*) \\ &\quad - |\Phi_\lambda(\mathcal{C}) - \bar{\Phi}_\lambda(\mathcal{C}) - \Phi_\lambda(\mathcal{C}^*) + \bar{\Phi}_\lambda(\mathcal{C}^*)| \\ &\geq \left(c - C \sqrt{\frac{sn^* \log N}{Tp_{\min}^2}} \right) r^2 - C\lambda\sqrt{s}Kr\end{aligned}$$

Hence $\Phi_\lambda(\hat{\mathcal{C}}) \leq \Phi_\lambda(\mathcal{C}^*)$ yields

$$r \leq \lambda\sqrt{s}K$$

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