

# Functional Data Analysis of Generalized Quantile Regression

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# Generalized Quantile Regression (GQR)

- Quantiles and Expectiles are generalized quantiles, Jones (1994).
- Capture the tail behaviour of conditional distributions.
- Applications in finance, weather, demography,  $\dots$
- Some applications involve MANY GQR curves.



## Applications

- ▣ Finance: VaR and expected shortfall (ES)
- ▣ Labor: Wage with education levels
- ▣ Weather: Temperature and rainfall
  - ▶ Energy Company
  - ▶ Tourist Company
  - ▶ Farmers





Figure 1: Land before and after the flood



## Weather Derivatives

A CAT temperature future under the non-arbitrage pricing setting:

$$\begin{aligned} F_{CAT}(t, \tau_1, \tau_2) &= E^{Q_\lambda} \left[ \int_{\tau_1}^{\tau_2} T_u du | \mathcal{F}_t \right] \\ &= \int_{\tau_1}^{\tau_2} \Lambda_u du + \mathbf{a}_{t, \tau_1, \tau_2} \mathbf{X}_t + \int_t^{\tau_1} \lambda_u \sigma_u \mathbf{a}_{t, \tau_1, \tau_2} \mathbf{e}_L du \\ &\quad + \int_{\tau_1}^{\tau_2} \lambda_u \sigma_u \mathbf{e}_1^\top \mathbf{A}^{-1} [\exp \{ \mathbf{A}(\tau_2 - u) \} - I_L] \mathbf{e}_L du \quad (1) \end{aligned}$$

where  $\lambda_u$  is market price of risk, and  $\sigma_u$  is the volatility of temperature.

To estimate  $\sigma_u$  more accurately is to price the futures more precisely.



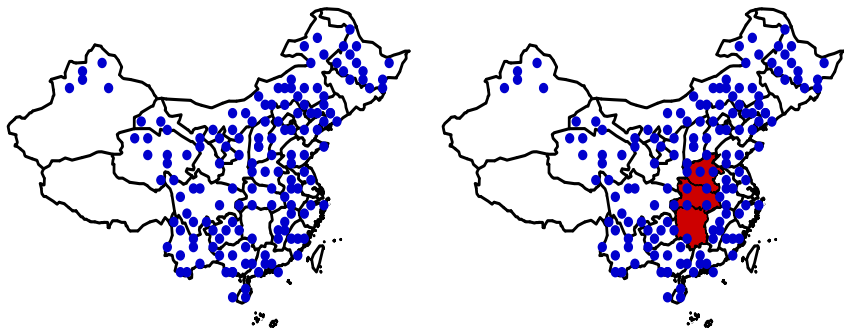


Figure 2: Weather Stations in China



## Statistical Challenges

- ▣ Traditional: estimate GQR individually
- ▣ Directly: estimate GQR jointly
- ▣ common structure neglected
- ▣ too many parameters, curse of dimensionality



## Functional Data Analysis (FDA)

- a tool to capture random curves
- consider dependencies between individuals
- FPCA a tool to reduce dimensionality
- interpretation of factors
- apply “FPCA” and least asymmetric weighted squares (LAWS)





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# Outline

1. Motivation ✓
2. Generalized Quantile Estimation
3. FDA for GQR
4. Simulation
5. Application
6. Conclusion



## Quantile and Expectile

Quantile

$$F(l) = \int_{-\infty}^l dF(y) = \tau$$

$$l = F^{-1}(\tau)$$

Expectile

$$G(l) = \frac{\int_{-\infty}^l |y - l| dF(y)}{\int_{-\infty}^{\infty} |y - l| dF(y)} = \tau$$

$$l = G^{-1}(\tau)$$



## Loss Function

Loss function:

$$L(y, \theta) = |y - \theta|^\alpha \quad (2)$$

Asymmetric loss function for generalized quantiles:

$$\rho_\tau(u) = |\mathbf{I}(u \leq 0) - \tau| |u|^\alpha, \quad \tau \in (0, 1) \quad (3)$$

with  $\alpha \in \{1, 2\}$  and  $u = y - \theta$ .



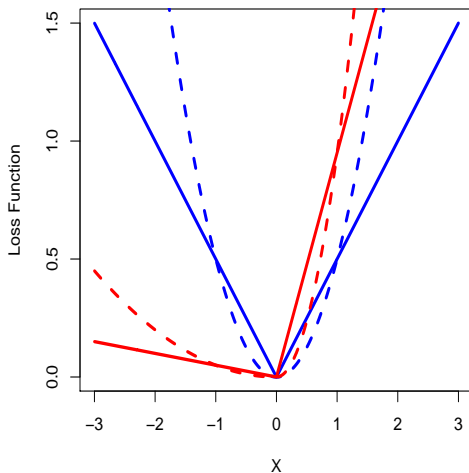


Figure 3: Loss functions for  $\tau = 0.9$  (red);  $\tau = 0.5$  (blue);  $\alpha = 1$  (solid line);  $\alpha = 2$  (dashed line).



## Weight

$$w_{\alpha}(u) = |\mathbf{I}(u \leq 0) - \tau| |u|^{(\alpha-2)} \quad (4)$$

Minimum contrast approach:

$$\begin{aligned} l_{\tau} &= \arg \min_{\theta} E\{\rho_{\tau}(Y - \theta)\} \\ &= \arg \min_{\theta} E w_{\alpha}(Y - \theta) |Y - \theta|^2 \end{aligned}$$

Generalized quantile regression curve:

$$\begin{aligned} l_{\tau}(t) &= \arg \min_{\theta} E\{\rho_{\tau}(Y - \theta) | X = t\} \\ &= \arg \min_{\theta} E\{w_{\alpha}(Y - \theta) |Y - \theta|^2 | X = t\} \end{aligned}$$



## Estimation Method

### □ Kernel Smoothing

- ▶ Quantile: Fan et.al (1994)
- ▶ Expectile: Zhang (1994)

### □ Penalized Spline Smoothing

- ▶ Quantile: Koenker et.al (1994)
- ▶ Expectile: Schnabel and Eilers (2009)

GQR can be estimated by Iterated Reweighted Asymmetric Least Square.



## Single Curve Estimation

Rewrite as regression pb:

$$Y_t = I(t) + \varepsilon_t \quad (5)$$

where  $F_{\varepsilon|t}^{-1}(\tau) = 0$  and  $G_{\varepsilon|t}^{-1}(\tau) = 0$ .

Approximate  $I(\cdot)$  by a B-spline basis:

$$I(t) = b(t)^\top \theta_\mu \quad (6)$$

where  $b(t) = \{b_1(t), \dots, b_q(t)\}^\top$  is a vector of cubic B-spline basis and  $\theta_\mu$  is a vector with dimension  $q$ .



## Estimation

Employ a roughness penalty:

$$S(\theta_\mu) = \sum_{t=1}^T w_t \{Y_t - b(t)^\top \theta_\mu\}^2 + \lambda \{ \theta_\mu^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_\mu \} \quad (7)$$

where  $Y = (Y_1, Y_2, \dots, Y_T)^\top$ ,  $\ddot{b}(t) = \frac{\partial^2 b(t)}{\partial t^2}$  and  $w_t = w_\alpha \{Y_t - I(t)\}$  ( $I(t)$  known).





## Estimation

The generalized quantile curve:

$$\begin{aligned}\hat{\theta}_{\mu} &= \arg \min_{\theta_{\mu}} S(\theta_{\mu}) \\ &= \{B^{\top}WB + \lambda \int \ddot{b}(t)\ddot{b}(t)^{\top} dt\}^{-1}(B^{\top}WY)\end{aligned}$$

$B = \{b(t)\}_{t=1}^T$  is the spline basis matrix with dimension  $T \times q$ , and  $W = \text{diag}\{w_t\}$  defined in (4):

$$\hat{l}(t) = b(t)\hat{\theta}_{\mu} \quad (8)$$



## Regression Model

$$Y_{ij} = l_i(t_{ij}) + \varepsilon_{ij} \quad (9)$$

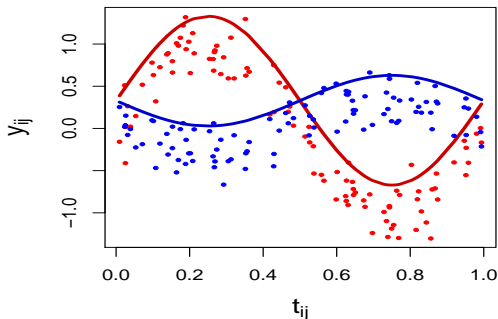


Figure 4: Data design with  $\tau = 0.95$ .  design



## Mixed effect Model

Observe  $i = 1, \dots, N$  individual curves:

$$l_i(t) = \mu(t) + v_i(t) \quad (10)$$

- $\mu(t)$  common shape
- $v_i(t)$  departure from  $\mu(t)$ .

Approximate via

$$l_{ij} = l_i(t_{ij}) = b(t_{ij})^\top \theta_\mu + b(t_{ij})^\top \gamma_{ij} \quad (11)$$

where  $i = 1, \dots, N$  and  $j = 1, \dots, T_i$ .

- Too many parameters to estimate.
- Very volatile for sparse data, James et.al (2000).



## Reduced Model

► Mercer's Lemma

► Karhunen-Loève Theorem

$$l_i(t) = \mu(t) + \sum_{k=1}^K f_k(t) \alpha_{ik} \quad (12)$$

□  $K$  the number of factors and  $f_k$   $k$ -th factor:

$$f(t) = \{f_1(t), \dots, f_K(t)\}^\top$$

□  $\alpha_i = (\alpha_{i1}, \dots, \alpha_{iK})^\top$  random scores.

Representation of  $\mu$  and  $f$ :

$$\begin{aligned} \mu(t) &= b(t)^\top \theta_\mu \\ f(t)^\top &= b(t)^\top \Theta_f \end{aligned}$$

where  $\theta_\mu \in R^q$  and  $\Theta_f$  with dimension  $q \times K$ .



## Reduced Model

Rewrite (12)

$$l_{ij} = l_i(t_{ij}) = b(t_{ij})^\top \theta_\mu + b(t_{ij})^\top \Theta_f \alpha_i \quad (13)$$

With  $L_i = \{l_i(t_1), \dots, l_i(T_i)\}^\top$ ,  $B_i = \{b(t_1), \dots, b(T_i)\}^\top$ , the GQR curves:

$$L_i = B_i \theta_\mu + B_i \Theta_f \alpha_i \quad (14)$$

Then the model reads:

$$Y_i = L_i + \varepsilon_i = B_i \theta_\mu + B_i \Theta_f \alpha_i + \varepsilon_i \quad (15)$$

with  $Y_i$  is  $T_i \times 1$  and  $\alpha_i$  is  $K \times 1$ .



## Constraints

Orthogonality requirements of the factors:

$$\int f(t)f(t)^{\top} dt = \Theta_f^{\top} \int b(t)^{\top} b(t) dt \Theta_f = I_K$$

That is to say

$$\begin{aligned}\Theta_f^{\top} \Theta_f &= I_K \\ \int b(t)^{\top} b(t) dt &= I_q\end{aligned}$$



## "Empirical" Loss Function

For the GQR regression:

$$S = \sum_{i=1}^N \sum_{j=1}^{T_i} w_{ij} \{Y_{ij} - b(t_j)^\top \theta_\mu - b(t_j)^\top \Theta_f \alpha_i\}^2 \quad (16)$$

Roughness penalty:

$$M_\mu = \theta_\mu^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_\mu$$
$$M_f = \sum_{k=1}^K \theta_{kf}^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_{kf}$$

And  $w_{ij} = w_\alpha(Y_{ij} - l_{ij})$ , where  $l_{ij}$  defined in (13).



## LAWS

$$\begin{aligned} S^* &= S + \lambda_\mu M_\mu + \lambda_f M_f \\ &= \sum_{i=1}^N (Y_i - B_i \theta_\mu - B_i \Theta_f \alpha_i)^\top W_i (Y_i - B_i \theta_\mu - B_i \Theta_f \alpha_i) \\ &\quad + \lambda_\mu \{ \theta_\mu^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_\mu \} \\ &\quad + \lambda_f \{ \sum_{k=1}^K \theta_{f,k}^\top \int \ddot{b}(t) \ddot{b}(t)^\top dt \theta_{f,k} \} \end{aligned} \tag{17}$$

where  $\theta_{f,k}$  is the  $k$ -th column in  $\Theta_f$ .





## Solutions

Minimizing  $S^*$ :

$$\begin{aligned}\hat{\theta}_{\mu} &= \left\{ \sum_{i=1}^N B_i^{\top} W_i B_i + \lambda_{\mu} \int \ddot{b}(t) \ddot{b}(t)^{\top} dt \right\}^{-1} \\ &\quad \left\{ \sum_{i=1}^N B_i^{\top} W_i (Y_i - B_i \hat{\Theta}_f \hat{\alpha}_i) \right\} \\ \hat{\theta}_{f,j} &= \left\{ \sum_{i=1}^N \hat{\alpha}_{ij}^2 B_i^{\top} W_i B_i + \lambda_f \int \ddot{b}(t) \ddot{b}(t)^{\top} dt \right\}^{-1} \\ &\quad \left\{ \sum_{i=1}^N \hat{\alpha}_{ij} B_i^{\top} W_i (Y_i - B_i \hat{\theta}_{\mu} - B_i Q_{ij}) \right\} \quad (18)\end{aligned}$$



$$\hat{\alpha}_i = \left\{ \hat{\Theta}_f^\top B_i^\top W_i B_i \hat{\Theta}_f \right\}^{-1} \left\{ \hat{\Theta}_f^\top B_i^\top W_i (Y_i - B_i \hat{\theta}_\mu) \right\} \quad (19)$$

Where

$$Q_{ij} = \sum_{k \neq j} \hat{\theta}_{f,k} \hat{\alpha}_{ik}$$

and  $i = 1, \dots, N, j = 1, \dots, K$ .

□ initial values

► Details

□ updated procedure

► Details



## Auxiliary Parameters

- Number of knots is not crucial, James et.al (2000)
- Use 5-fold cross validation (CV) to choose the number of factors and the penalty parameters
- Define an index function  $\kappa : \{1, \dots, N\} \rightarrow \{1, \dots, 5\}$  and  $\widehat{l}_i(\cdot)^{-\kappa(i)}$  denote the estimated  $i$ th generalized quantile function using data excluding those in the fold of  $\kappa(i)$ .

$$CV(K, \lambda_\mu, \lambda_f) = \frac{1}{\sum_{i=1}^N T_i} \sum_{i=1}^N \sum_{j=1}^{T_i} \rho_\tau \{Y_{ij} - \widehat{l}_i^{-\kappa(i)}(t_{ij})\}$$



## Simulation

$$Y_{ij} = \mu(t_j) + f_1(t_j)\alpha_{1i} + f_2(t_j)\alpha_{2i} + e_{ij} \quad (20)$$

with  $i = 1, \dots, N$ ,  $j = 1, \dots, T_i$  and  $t_j$  is equal distanced on  $[0, 1]$ .

The common shape curve and factor functions:

$$\mu(t) = 1 + t + \exp\{-(t - 0.6)^2/0.05\}$$

$$f_1(t) = \sin(2\pi t)/\sqrt{0.5}$$

$$f_2(t) = \cos(2\pi t)/\sqrt{0.5}$$

where  $\alpha_{1i} \sim N(0, 36)$ ,  $\alpha_{2i} \sim N(0, 9)$ .



## Scenarios

- ▣  $e_{ij} \sim N(0, 0.5)$
- ▣  $e_{ij} \sim N(0, \mu(t) \times 0.5)$
- ▣  $e_{ij} \sim t(5)$
  
- ▣ small sample:  $N = 20, T = T_i = 100$
- ▣ large sample:  $N = 40, T = T_i = 150$

Theoretical  $\tau$  quantile and expectile for individual  $i$ :

$$l_{ij} = \mu(t_j) + f_1(t_j)\alpha_{1i} + f_2(t_j)\alpha_{2i} + \varepsilon_{ij}$$

where  $\varepsilon_{ij}$  represents the corresponding theoretical  $\tau$ -th quantile and expectile of the distribution of  $e_{ij}$  ( $\varepsilon_{ij} = e_{ij} + \sqrt{0.5} \cdot \Phi^{-1}(\tau)$ ).



## Estimators

- The individual curve:

$$\begin{aligned}l_i &= \mu + \sum_{k=1}^K f_k \alpha_{ik} \\ \hat{l}_{i,fp} &= B_i \hat{\theta}_\mu + B_i \hat{\Theta}_f \hat{\alpha}_i \\ \hat{l}_{i,in} &: \text{Single curve, see (8)}\end{aligned}$$

- The mean curve:

$$\begin{aligned}m &= \mu(t) + e_\tau \\ m_{fp} &= \frac{1}{N} \sum_{i=1}^N B_i \hat{\theta}_\mu \\ m_{in} &= \frac{1}{N} \sum_{i=1}^N \hat{l}_{i,in}\end{aligned}\tag{21}$$



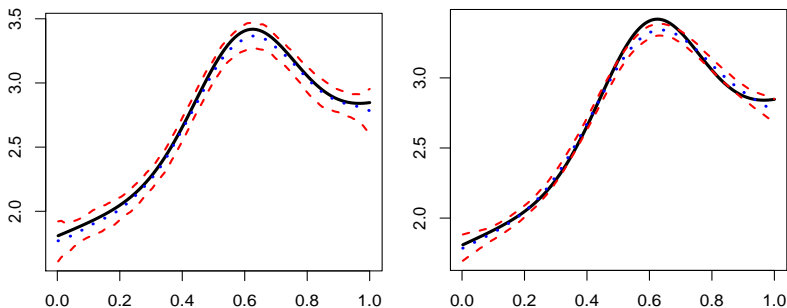


Figure 5: The estimated  $\mu$  (blue dotted), the real  $\mu$  (black solid) and the 5% – 95% pointwise confidence intervals (red dashed) for 95% expectile curves when the error term is normally distributed with mean 0 and variance 0.5. The sample sizes are respectively  $N = 20, M = 100$  (Left) and  $N = 40, M = 150$  (Right).



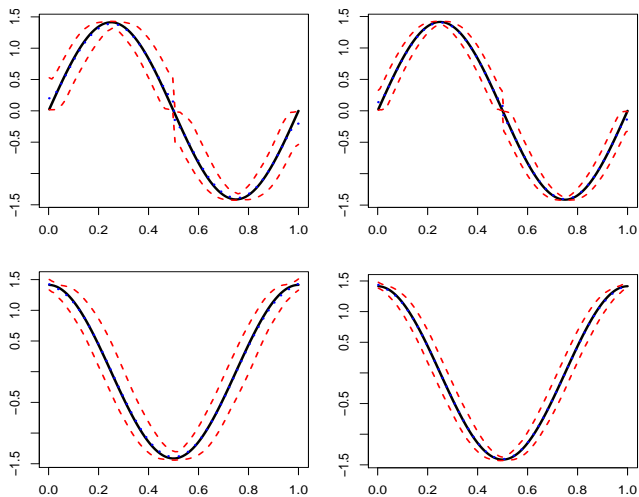


Figure 6: The estimated first and second principal components  $f_1$  and  $f_2$ .  
FDA of GQR





Scenario	Sample Size	Expectile curves		Quantile curves	
		FDA	Separate	FDA	Separate
1	$N = 20, T = 100$	0.0815	0.1407	0.1733	0.2539
		(0.0296)	(0.0149)	(0.0283)	(0.0227)
	$N = 40, T = 150$	0.0189	0.0709	0.0723	0.1875
		(0.0025)	(0.0052)	(0.1205)	(0.0127)
2	$N = 20, T = 100$	0.1436	0.3188	0.2769	0.8039
		(0.0248)	(0.0339)	(0.1061)	(0.0860)
	$N = 40, T = 150$	0.0931	0.2751	0.1785	0.6029
		(0.0106)	(0.0188)	(0.0813)	(0.0503)
3	$N = 20, T = 100$	0.2859	0.5194	0.4490	1.2227
		(0.0525)	(0.1284)	(0.2867)	(0.2290)
	$N = 40, T = 150$	0.1531	0.4087	0.2340	0.8683
		(0.0212)	(0.0707)	(0.1259)	(0.1085)

Table 1: The summary statistics (mean and SD) of the MSEs for estimating 95% generalized quantile curves by the FDA approach and the separate estimation approach. Scenario 1 with  $\varepsilon_{ij} \sim N(0, 0.5)$ , Scenario 2 with  $\varepsilon_{ij} \sim N(0, \mu(t) \times 0.5)$  and Scenario 3 with  $\varepsilon_{ij} \sim t(5)$ .



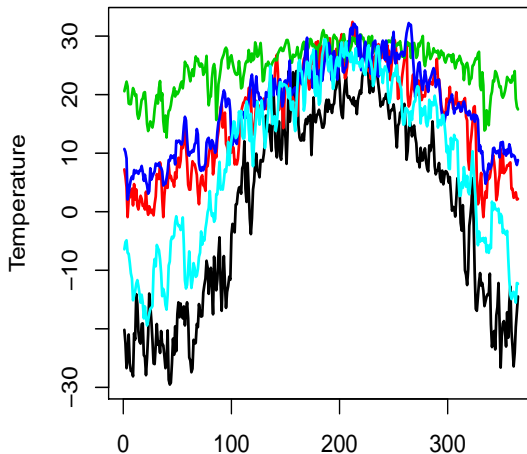


Figure 7: Time series plot of 5 selected weather stations (south, north, east, west and middle) from 150 weather stations in China



## Data

Let  $T_{it}$  denote the average temperature on day  $t$  for city (station)  $i$ . The standard model described is:

$$\begin{aligned}T_{it} &= X_{it} + \Lambda_{it}, \\ \Lambda_{it} &= a_i + b_i t + \sum_{m=1}^M c_{im} \cos \left\{ \frac{2\pi(t - d_{im})}{m \cdot 365} \right\}, \\ X_{it} &= \sum_{j=1}^{p_i} \beta_{ij} X_{i,t-j} + \varepsilon_{it}.\end{aligned}\tag{22}$$



PC index	Expectile levels			
	5%	25%	75%	95%
1	0.3833	0.0596	0.0659	0.4421
2	0.0665	0.0131	0.0194	0.1102
3	0.0471	0.0077	0.0158	0.0746
4	0.0415	0.0074	0.0123	0.0657
5	0.0306	0.0072	0.0056	0.0455
6	0.0262	0.0051	0.0050	0.0226

Table 2: The empirical variances of PC scores for the Chinese temperature data.



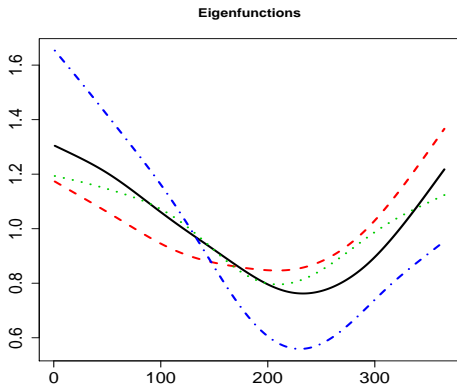


Figure 8: The estimated first principal component for the 5% (black solid), 25% (red dashed), 75% (green dotted), 95% (blue dash-dotted) expectiles curves of the volatility of the temperature of China in 2010 with the data from 150 weather stations.



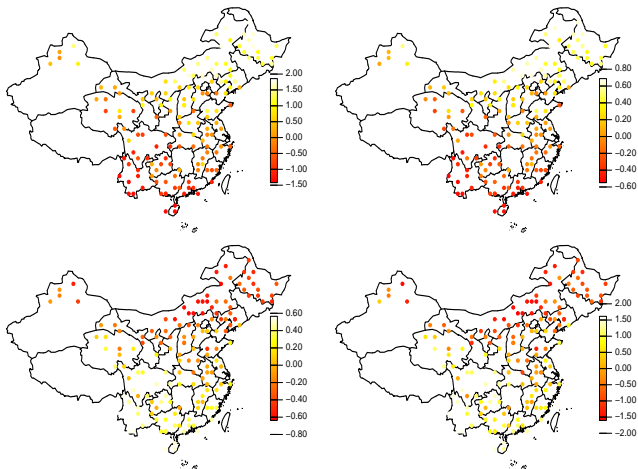


Figure 9: The estimated first principal component scores  $\alpha_1$  for the 5%, 25%, 75% and 95% expectile curves of the temperature distribution.



## Conclusion

- Dimension Reduction technique applied to a nonlinear object.
- Provides a novel way to estimate several generalized quantile curves simultaneously.
- Outperforms the single curve estimation, especially when the data is very volatile.
- Pricing weather derivatives more precisely can be possible.



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## Volatility of Temperature

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- The temperature  $T_{it}$  on day  $t$  for city  $i$ :

$$T_{it} = X_{it} + \Lambda_{it}$$

- The seasonal effect  $\Lambda_{it}$ :

$$\Lambda_{it} = a_i + b_i t + \sum_{m=1}^M c_{im} \cos\left\{\frac{2\pi(t - d_{im})}{365}\right\}$$

- $X_{it}$  follows an  $AR(p_i)$  process:

$$X_{it} = \sum_{j=1}^{p_i} \beta_{ij} X_{i,t-j} + \varepsilon_{it} \quad (23)$$

$$\hat{\varepsilon}_{it} = X_{it} - \sum_{j=1}^{p_i} \hat{\beta}_{ij} X_{i,t-j}$$



## Initial Values

[▶ Return](#)

1. Estimate  $N$  single curves  $\hat{l}_i$  individually.
2. Linear regression for  $\hat{\theta}_{\mu 0}$ :  $\hat{l}_i = B_i \theta_{\mu} + \varepsilon_i$
3. Calculate  $\tilde{l}_{i0} = \hat{l}_i - B_i \hat{\theta}_{\mu 0}$ , and  $\hat{\Gamma}_0 = (\hat{\Gamma}_{10}, \dots, \hat{\Gamma}_{N0})$ .

$$\tilde{l}_{i0} = B_i \Gamma_i + \varepsilon_i$$

4. Apply SVD to decompose  $\hat{\Gamma}_{i0}$ :

$$\hat{\Gamma}_{i0} = U D V^T = \Theta_{f0} \alpha_{i0}$$

5. Choose the first  $K$  factors from  $U$  as  $\hat{\Theta}_{f0}$ , and regress  $\hat{\Gamma}_{i0}$  on  $\hat{\Theta}_{f0}$  to get  $\hat{\alpha}_{i0}$ :

$$\hat{\Gamma}_{i0} = \hat{\Theta}_{f0}(\alpha_{i1}, \dots, \alpha_{iK}) + \varepsilon_i \quad (24)$$



## Update Procedure

[▶ Return](#)

1. Plug  $\hat{\Theta}_{f0}$  and  $\hat{\alpha}_{i0}$  into (18) to update  $\theta_{\mu}$ , and get  $\hat{\theta}_{\mu1}$ .
2. Plugging  $\hat{\theta}_{\mu1}$  and  $\hat{\alpha}_{i0}$  into the second equation of (18) gives  $\hat{\Theta}_{f1}$ .
3. Given  $\hat{\theta}_{\mu1}$  and  $\hat{\Theta}_{f1}$ , estimate  $\hat{\alpha}_i$ .
4. Recalculate the weight matrix:

$$w'_{ij} = w_{\alpha}(Y_{ij} - \hat{l}_{ij})$$

where  $\hat{l}_{ij}$  is the  $j$ -th element in  $\hat{l}_i = B_i \hat{\theta}_{\mu1} + B_i \hat{\Theta}_{f1} \hat{\alpha}_i$

5. Repeat step (1) to (4) until the solutions converge.



## Mercer's Lemma

The covariance operator  $K$

$$K(s, t) = \text{Cov}\{I(s), I(t)\}, E\{I(t)\} = \mu(t), s, t \in \mathcal{T} \quad (25)$$

There exists an orthonormal sequence  $(\psi_j)$  and non-increasing and non-negative sequence  $(\kappa_j)$ ,

$$\begin{aligned}(K\psi_j)(s) &= \kappa_j\psi_j(s) \\ K(s, t) &= \sum_{j=1}^{\infty} \kappa_j\psi_j(s)\psi_j(t) \\ \sum_{j=1}^{\infty} \kappa_j &= \int_I K(t, t)dt < \infty\end{aligned} \quad (26)$$

► Return



## Karhunen-Loève Theorem

Under assumptions of Mercer's lemma

$$l(t) = \mu(t) + \sum_{j=1}^{\infty} \sqrt{\kappa_j} \xi_j \psi_j(t) \quad (27)$$

where  $\xi_j \stackrel{\text{def}}{=} \frac{1}{\sqrt{\kappa_j}} \int l(t) \psi_j(s) ds$ , and  $E(\xi_j) = 0$

$$E(\xi_j \xi_k) = \delta_{j,k} \quad j, k \in \mathbb{N}$$

and  $\delta_{j,k}$  is the Kronecker delta.

► Return

