Nonparametric Estimation of Additive Models with Homogeneous Components

Wolfgang Härdle<br>Woocheol Kim

Gautam Tripathi


Sonderforschungsbereich 373
Wirtschaftswissenschaftliche Fakultät
Humboldt-Universität zu Berlin
sfb.wiwi.hu-berlin.de


A function, $f(\cdot)$ is homogeneous of degree $\alpha$, if

$$
f\left(\lambda x_{1}, . ., \lambda x_{d}\right)=\lambda^{\alpha} f\left(x_{1}, . ., x_{d}\right) .
$$

Examples:
i) Linear models: $f(x)=x^{T} \beta \quad(\alpha=1)$
ii) Cobb-Douglas : $f(x)=x_{1}^{\alpha_{1}} x_{2}^{\alpha_{2}},\left(\alpha=\alpha_{1}+\alpha_{2}\right)$
iii) CRS-technology: $f(x)=a\left(x_{1}^{\rho}+x_{2}^{\rho}\right)^{1 / \rho},(\alpha=1)$


Why is the concept of homogeneity important ?

- Characterization of production functions

$$
\begin{aligned}
& \alpha<1 \\
& \alpha=1 \\
& \alpha>1
\end{aligned} \Longleftrightarrow \quad \begin{gathered}
\text { conseasing } \\
\text { constant } \\
\text { increasing }
\end{gathered}
$$

- In the theory of producers,
cost-minimizing(profit-maximizing) behavior of competitive firms implies their cost(profit) functions are linearly homogeneous in input (and output) prices.

$$
\begin{gathered}
C=c\left(y, p_{I}\right) \text { s.t. } c\left(y, \lambda p_{I},\right)=\lambda c\left(y, p_{I}\right) \\
\pi=\pi\left(p_{I}, p_{O}\right) \text { s.t. } \pi\left(\lambda p_{I}, \lambda p_{O}\right)=\lambda \pi\left(p_{I}, p_{O}\right)
\end{gathered}
$$



## Nonparametric Models with Homogeneous Restriction

- The estimation has been carried out only in parametric forms. Christensen and Greene (1976) analyzed the cost function of electricity generation in the US with inputs of capital, labor, and fuel.
- Partial Linear Model. Tripathi (2000) 'efficiency bound for $\beta$ ' with homogeneous $f(\cdot)$ :

$$
Y_{i}=Z_{i}^{T} \beta+f\left(X_{i}\right)+\varepsilon_{i}
$$

- Nonparametric Model. Tripathi and Kim (1999) with homogeneous $f(\cdot)$ :

$$
Y_{i}=f\left(X_{i}\right)+\varepsilon_{i}
$$



## Objective

Analyze nonparametric additive models where at least one component is restricted to be homogeneous.

$$
\begin{array}{r}
Y_{i}=f_{1}\left(X_{i}\right)+f_{2}\left(Z_{i}\right)+\varepsilon_{i}, \quad\left(\varepsilon_{i}: \text { i.i.d. }\right), \\
\\
\quad \text { where } f_{1}(\cdot) \text { is homogeneous. }
\end{array}
$$

## Example:

## $Y_{i}$ : total costs

$f_{1}\left(X_{i}\right)$ : variable costs (capital, labor,...)
$f_{2}\left(Z_{i}\right)$ : fixed costs


## Extension

## an option pricing model

Consider a nonparametric option pricing model,

$$
\Pi_{t}=f_{1}\left(S_{t}, K, T-t, X_{t}\right),
$$

$\Pi_{t}=$ option price
$S_{t}=$ price of underlying asset
$K=$ exercise price
$T-t=$ time to expiration
$X_{t}=$ other var. ( $S_{t-1}$ or volatility).
Garcia and Renault (1996) showed $f_{1}(\cdot)$ is homogeneous of degree one in $\left(S_{t}, K\right)$.

Under multiplicative assumption, the pricing model is

$$
\Pi_{t}=f_{1}\left(S_{t}, K\right) f_{2}\left(T-t, X_{t}\right),
$$

where $f_{1}(\cdot)$ is linearly homogeneous.


## Imposing Homogeneity

## Numeraire Approach

From the homogeneity,
$f_{1}\left(X_{1 i}, . ., X_{d i}\right)=X_{d i}^{\alpha_{1}} f_{1}\left(X_{1 i} / X_{d i}, . ., X_{(d-1) i} / X_{d i}, 1\right)$.
By defining
$\beta_{1}\left(U_{i}\right)=f_{1}\left(X_{1 i} / X_{d i}, . ., X_{(d-1) i} / X_{d i}, 1\right)$ with $U=\left(X_{1 i} / X_{d i}, . ., X_{(d-1) i} / X_{d i}, 1\right)$, reparametrize into

$$
\begin{equation*}
Y_{i}=X_{d i}^{\alpha_{1}} \beta_{1}\left(U_{i}\right)+f_{2}\left(Z_{i}\right)+\varepsilon_{i} . \tag{1}
\end{equation*}
$$

Since $\alpha$ is known, we only estimate $\beta_{1}(\cdot)$ and construct $\widehat{f}_{1}(x)=x_{d}^{\alpha_{1}} \widehat{\beta}_{1}(u)$.


## General Model

Assume $f_{2}(\cdot)$ is also homogeneous, then,

$$
\begin{equation*}
Y_{i}=X_{d i}^{\alpha_{1}} \beta_{1}\left(U_{i}\right)+Z_{s i}^{\alpha_{2}} \beta_{2}\left(V_{i}\right)+\varepsilon_{i} . \tag{2}
\end{equation*}
$$

With $Z_{s i}=1$ and $V_{i}=Z_{i}$, (2) includes (1) as a special case.

Additional Contribution: We extend the theory for Varying-Coefficients Models by Hastie and Tibshirani (1997) or Functional Coefficients AR models by Tsay (1993).

$$
\begin{aligned}
& Y_{i}=\sum_{k=1}^{d} X_{k i} \beta_{k}\left(X_{(d+1) i}\right)+\varepsilon_{i}, \\
& Y_{i}=\sum_{k=1}^{d} Y_{i-k} \beta_{k}\left(Y_{i-d^{\prime}}\right)+\varepsilon_{i}
\end{aligned}
$$

## Two-Step Estimation Procedure

$$
Y_{i}=X_{d i}^{\alpha_{1}} \beta_{1}\left(U_{i}\right)+Z_{s i}^{\alpha_{2}} \beta_{2}\left(V_{i}\right)+\varepsilon_{i}
$$

## Local Linear Fit :First Step

After locally approximating $\beta_{1}(\cdot)$ and $\beta(\cdot)$ by linear equations,

$$
\begin{aligned}
& \min _{b_{1 k} ' s, b_{2 k} ' s} \frac{1}{n} \sum_{i=1}^{n} K_{h}\left(W_{i}-w\right) \times\left[y_{i}-\left\{b_{10}+\right.\right. \\
& \left.\left.\sum_{k=1}^{d-1} b_{1 k}\left(\frac{U_{k i}-u_{k}}{h_{1}}\right)\right\} X_{d i}^{\alpha_{1}}-\left\{b_{20}+\sum_{k=1}^{s-1} b_{2 k}\left(\frac{V_{k i}-v_{k}}{h_{2}}\right)\right\} Z_{s i}^{\alpha_{2}}\right]^{2} \\
& \text { where } w=(u, v) \text { and } W_{i}=\left(U_{i}, V_{i}\right) .
\end{aligned}
$$



- Note that $\widehat{b}_{10}$, the estimate of $\beta_{1}(u)$, also depends on the value of $v$. Thus, we denote the level estimates by

$$
\left[\begin{array}{l}
\widehat{\beta}_{1}(u, v) \\
\widehat{\beta}_{2}(u, v)
\end{array}\right]=\left[\begin{array}{l}
\widehat{b}_{10} \\
\widehat{b}_{20}
\end{array}\right] .
$$

- These estimates are consistent, but their convergence rates $\left(n^{\left.\frac{2}{4+(d+s-2)}\right)}\right.$ are not optimal, slower than $n^{\frac{2}{4+(d-1)}}$ or $n^{\frac{2}{4+(s-1)}}$. This is a natural result due to the use of the kernel weights, $K_{h}\left(W_{i}-w\right)$, of dimension, $(d+s-2)$ in our smoothing method.



## Marginal Integration: Second Step

- For the optimal convergence rate, marginally integrate the pilot estimates of $\widehat{\beta}_{10}\left(u, V_{i}\right)$ over $V_{i} i=1, . ., n$, i.e.,

$$
\widehat{\beta}_{10}^{*}(u)=\frac{1}{n} \sum_{i=1}^{n} \widehat{\beta}_{10}\left(u, V_{i}\right),
$$

similarly,

$$
\widehat{\beta}_{20}^{*}(v)=\frac{1}{n} \sum_{i=1}^{n} \widehat{\beta}_{20}\left(U_{i}, v\right) .
$$



## Marginal Integration

Newey (1994), Tjøstheim and Auestadt (1994), and Linton and Nielsen (1995)

- Advantage: theoretical tractability in deriving asymptotic properties, in contrast to backfitting
- Weakness: high costs of computations
- alternative: Instrumental Variable approach by Kim (1998)

Finally, for the regression surface, we use $\widehat{f}^{*}(x, z)=x_{d}^{\alpha_{1}} \widehat{\beta}_{1}^{*}(u)+z_{s}^{\alpha_{2}} \widehat{\beta}_{2}^{*}(v)$


## Conditions

A1. $\left\{Y_{i}, X_{i}, Z_{i}\right\}_{i=1}^{n}$ is a random sample, and $\varepsilon_{i}$ is i.i.d. with $E(\varepsilon \mid X, Z)=0$ and $E\left(\varepsilon^{2} \mid X, Z\right)=\sigma^{2}(X, Z)<\infty$.

A2. (Continuity and Differentiability) The functions of the components, varying-coefficients, and conditional variance, together with the densities(marginal or joint)- $f_{1}(\cdot), f_{2}(\cdot)$, $\beta_{1}(\cdot), \beta_{2}(\cdot) \sigma(\cdot), p_{X}(\cdot), p_{Z}(\cdot)$ and $p_{X, Z}(\cdot)$ are continuous (and hence bounded on the compact support) and twice differentiable with bounded partial derivatives.

A3. (Density Functions) $p_{X}(\cdot), p_{Z}(\cdot)$ and $p_{X, Z}(\cdot)$ are bounded away from zero on the compact supports. Also, conditional density exists and is bounded.

A4. The matrix $E\left(W^{T} W \mid X_{d}=x_{d}, Z_{s}=z_{s}\right)$ is of full rank, and $E\left(W^{T} W \mid X_{d}=x_{d}, Z_{s}=z_{s}\right)^{-1}$ is bounded element-wise in a neighborhood of $\left(x_{d}, z_{s}\right)$.

A5. (Kernel Functions) The kernel function $K$ is positive, compactly supported bounded function, with $\int K(u) d u=1$ and $\int u K(u) d u=0 .\left|K\left(x_{1}\right)-K\left(x_{2}\right)\right|<c\left|x_{1}-x_{2}\right|$ for all $x_{1}$ and $x_{2}$ in its support.

A6. (Bandwidth Condition 1) $h_{1}=$
$h_{2}=h \rightarrow 0$ and $n h^{d+s-2} \rightarrow \infty$.
A7. (Bandwidth Condition 2)
$n h_{1}^{(d-1)} h_{2}^{2(s-1)} / \ln ^{2} n \rightarrow \infty$,
$h_{2}^{(s-1)} / h_{1}^{2} \rightarrow \infty, h_{1} \rightarrow 0$, and $n h_{1} \rightarrow \infty$.


## Main Results I

Notation:
$w=\left(w_{1}, w_{2}\right)=(u, v), \widehat{\beta}_{0}(w)=\left(\widehat{\beta}_{10}(w), \widehat{\beta}_{20}(w)\right)$
Theorem 1. Assume that the conditions of A. 1 through A. 6 hold. Then,

$$
\begin{aligned}
& \sqrt{n h^{d+s-2}}\left[\widehat{\beta}_{0}(w)-\beta_{0}(w)-B I A S\right] \\
& \xrightarrow{\mathcal{L}} N\left(0, \frac{\|K\|_{2}^{2}}{p_{W}(w)} \Sigma_{\beta}\right)
\end{aligned}
$$

where
$\mu_{K}^{2}=\int K(u) u^{2} d u$, and $\|K\|_{2}^{2}=\int K^{2}(r) d r$.


$$
\begin{aligned}
& B I A S=\frac{h^{2}}{2} \mu_{K}^{2} \times \\
& {\left[\begin{array}{c}
\operatorname{tr}\left(D^{2} \beta_{1}\left(w_{1}\right)\right)+\frac{E\left(X_{d}^{\alpha_{1}} Z_{s}^{\alpha_{2}} \mid W=w\right)}{E\left(X_{d}^{2 \alpha_{1}} \mid W=w\right)} \operatorname{tr}\left(D^{2} \beta_{2}\left(w_{2}\right)\right) \\
\operatorname{tr}\left(D^{2} \beta_{2}\left(w_{2}\right)\right)+\frac{E\left(X_{d}^{\alpha_{1}} Z_{s}^{\alpha_{2}} \mid W=w\right)}{E\left(Z_{s}^{2 \alpha_{2}} \mid W=w\right)} \operatorname{tr}\left(D^{2} \beta_{1}\left(w_{1}\right)\right)
\end{array}\right]} \\
& \Sigma_{\beta}(W) \equiv \\
& {\left[\begin{array}{cc}
\frac{E_{\mid W}\left(X_{d}^{2 \alpha_{1}} \sigma_{\varepsilon}^{2}\left(W, X_{d}, Z_{s}\right)\right)}{E_{\mid W}^{2}\left(X_{d}^{2 \alpha_{1}}\right)} & \frac{E_{\mid W}\left(X_{d}^{\alpha_{1}} Z_{s}^{\alpha_{2}} \sigma_{\varepsilon}^{2}\left(W, X_{d}, Z_{s}\right)\right)}{E_{\mid W}\left(X_{d}^{2 \alpha_{1}}\right) E_{\mid W}\left(Z_{s}^{2 \alpha_{2}}\right)} \\
\frac{E_{\mid W}\left(X_{d}^{\left.\alpha_{1} Z_{s}^{\alpha} \sigma_{\varepsilon}^{2}\left(W, X_{d}, Z_{s}\right)\right)}\right.}{E_{\mid W}\left(X_{d}^{2 \alpha_{1}}\right) E_{\mid W}\left(Z_{s}^{2 \alpha_{2}}\right)} & \frac{E_{\mid W}\left(Z_{s}^{2 \alpha_{2}} \sigma_{\varepsilon}^{2}\left(W, X_{d}, Z_{s}\right)\right)}{E_{\mid W}^{2}\left(Z_{s}^{2 \alpha_{2}}\right)}
\end{array}\right]}
\end{aligned}
$$



## Remark 2

- the convergence rate, $\sqrt{n h^{d+s-2}}$, from using the kernel function which is defined on $\mathbb{R}^{d-1} \times \mathbb{R}^{s-1}$.
- the bias of $\widehat{\beta}_{10}(u, v)$ is similar to the local linear fit in Fan (1992), a function of "second derivatives only", except that it depends on $D^{2} \beta_{2}(v)$, which is a natural extension of Tripathi and Kim (1999) dealing with $Y_{i}=X_{d i}^{\alpha_{1}} \beta_{1}\left(U_{i}\right)+\varepsilon_{i}$.
- For homoscedastic errors, the variance is $\|K\|_{2}^{2} \sigma_{\varepsilon}^{2} / p_{W}(w)$, the standard result.

From $\widehat{f}(x, z)=x_{d}^{\alpha_{1}} \widehat{\beta}_{1}(u)+z_{s}^{\alpha_{2}} \widehat{\beta}_{2}(v)$

Corollary 3. Under the same conditions of Theorem 1,

$$
\begin{aligned}
& \sqrt{n h^{d+s-2}}\left[\widehat{f}(x, z)-f(x, z)-B I A S_{f}\right] \\
& \xrightarrow{\mathcal{L}} N\left(0, \frac{\|K\|_{2}^{2}}{p_{W}(w)} \Sigma_{f}\right),
\end{aligned}
$$

$B I A S_{f}=\frac{h^{2}}{2}\left[x_{d}^{\alpha_{1}}, z_{s}^{\alpha_{2}}\right]^{T} B I A S$,

$$
\begin{aligned}
& \Sigma_{f}=\frac{x_{d}^{2 \alpha_{1}} E\left(X_{d}^{2 \alpha_{1}} \sigma_{\varepsilon}^{2}\left(W, X_{d}, Z_{s}\right) \mid W=w\right)}{E^{2}\left(X_{d}^{2 \alpha_{1}} \mid W=w\right)}+ \\
& 2 \frac{x_{d}^{\alpha_{1}} z_{s}^{\alpha_{2}} E\left(X_{d}^{\alpha_{1}} Z_{s}^{\alpha_{2}} \sigma_{\varepsilon}^{2}\left(W, X_{d}, Z_{s}\right) \mid W=w\right)}{E\left(X_{d}^{2 \alpha_{1}} \mid W=w\right) E\left(Z_{s}^{2 \alpha_{2}} \mid W=w\right)}+ \\
& \frac{z_{s}^{2 \alpha_{2}} E\left(Z_{s}^{2 \alpha_{2}} \sigma_{\varepsilon}^{2}\left(W, X_{d}, Z_{s}\right) \mid W=w\right)}{E^{2}\left(Z_{s}^{2 \alpha_{2}} \mid W=w\right)} .
\end{aligned}
$$

## Main Results II

Notation: $\widehat{\beta}_{1}^{*}(u)=\frac{1}{n} \sum_{j=1}^{n} \widehat{\beta}_{10}\left(u, V_{j}\right)$

Theorem 4 Under the conditions of A. 1 through A. 5 and A.7,
i) $\sqrt{n h_{1}^{d-1}}\left[\widehat{\beta}_{1}^{*}(u)-\beta_{1}(u)-B I A S^{*}(u)\right]$
$\xrightarrow{\mathcal{L}} N\left(0,\|K\|_{2}^{2} \Sigma_{\beta_{1}}\right)$,
$\Sigma_{\beta_{1}}=\int \frac{p_{V}^{2}\left(s_{2}\right)}{p_{W}\left(u, s_{2}\right)} \frac{E\left(X_{d}^{2 \alpha} \sigma_{\varepsilon}^{2}\left(W, X_{d}\right) \mid W=\left(u, s_{2}\right)\right)}{E^{2}\left(X_{d}^{2 \alpha_{1}} \mid W=\left(u, s_{2}\right)\right)} d s_{2}$,
$B I A S^{*}(u)=\mu_{K}^{2}\left[\frac{h_{1}^{2}}{2} \operatorname{tr}\left(D^{2} \beta_{1}(u)\right)+\right.$
$\left.\frac{h_{2}^{2}}{2} \int p_{V}(v) \frac{E\left(X_{d}^{\alpha_{1}} Z_{s}^{\alpha_{2}} \mid W=u, v\right)}{E\left(X_{d}^{2 \alpha_{1}} \mid W=u, v\right)} \operatorname{tr}\left(D^{2} \beta_{2}(v)\right) d v\right]$,


$$
\begin{aligned}
& \text { ii) } \sqrt{n h_{1}^{d-1}}\left[\widehat{f}_{\hat{f}}^{*}(x)-f_{1}(x)-B I A S_{f_{1}}^{*}(x)\right] \\
& \xrightarrow{\mathcal{L}} N\left(0,\|K\|_{2}^{2} \Sigma_{f_{1}}\right),
\end{aligned}
$$

$$
B I A S_{f_{1}}^{*}(x)=x_{d}^{\alpha_{1}} B I A S^{*}(u)
$$

$$
\Sigma_{f_{1}}=x_{d}^{2 \alpha_{1}} \int \frac{p_{V}^{2}\left(s_{2}\right)}{p_{W}\left(u, s_{2}\right)} \frac{E\left(X_{d}^{2 \alpha_{1}} \sigma_{\varepsilon}^{2}\left(W, X_{d}\right) \mid W=\left(u, s_{2}\right)\right)}{E^{2}\left(X_{d}^{2 \alpha_{1}} \mid W=\left(u, s_{2}\right)\right)} d s_{2} .
$$



## Remark 5

- Undersmoothing in a nuisance direction, $h_{2}^{2} / h_{1}^{2} \rightarrow 0, B I A S^{*}(u)=\frac{h_{1}^{2}}{2} \mu_{K}^{2} \operatorname{tr}\left(D^{2} \beta_{1}(u)\right)$.
- For homoscedastic errors, the variance is $\|K\|_{2}^{2} \sigma_{\varepsilon}^{2} \int \frac{p_{V}^{2}\left(s_{2}\right)}{p_{W}\left(u, s_{2}\right)} d s_{2}$.
- the same results from usual marginal integration in additive models with LLF as pilot estimate.



## Application: livestock production function in Wisconsin

Data Set: Farm Credit Service of Saint Paul, Minnesota (1987)
the number of observations, $N=\mathbf{2 5 0}$
$y$ : livestock
$x$ : family labor
$z_{1}$ : miscellaneous inputs (repairs, rent, supplies, gas, oil utilities)
$z_{2}$ : intermediate assets
$z_{3}$ : hired labor
$z_{4}$ :animal inputs (purchased feed, breeding, veterinary services)


## OLS based on Cobb-Douglas

$$
\begin{aligned}
& f(l)=c \prod_{i=1}^{5} l_{i}^{\beta_{i}} \\
& \widehat{\log y}= \underset{\substack{(0.289) \\
\\
\\
\\
\\
\underset{(0.3034)}{0.305} \log z_{2}} \underset{(0.020)}{0.063} \log x+\underset{(0.025)}{0.031} \log z_{3}+\underset{(0.023)}{0.289} \log z_{1}}{\substack{0.277}} \begin{aligned}
& 0.900 \\
& R^{2}= 0.9
\end{aligned} \\
& \sum_{i=1}^{5} \widehat{\beta}_{i}= 0.965
\end{aligned}
$$

At 1\% level, we cannot reject the hypothesis that $\sum_{i=1}^{5} \beta_{i}=1$, that is, cannot reject the hypothesis of CRS under a Cobb-Douglas specification.

Problems: the functional misspecification, homogeneity only on 'variable input', not on 'fixed input'


- Nonparametric Modeling Assumption:
fixed variable: family labor $(x)$
variable input: other inputs $\left(z_{1}, . ., z_{4}\right)$

$$
\begin{aligned}
y & =f_{1}(x)+f_{2}(z)+\varepsilon \quad: \text { additivity } \\
& =f_{1}(x)+z_{4} f_{2}\left(z_{1} / z_{4}, z_{2} / z_{4}, z_{3} / z_{4}, 1\right)+\varepsilon \\
& : \text { linear homogenity } \\
& =f_{1}(x)+z_{4} g_{2}\left(w_{1}, w_{2}, w_{3}\right)+\varepsilon, w_{i}=z_{i} / z_{4}
\end{aligned}
$$

* Severance-Lossin and Sperich (1997): componentwise additivity
no interaction between bariable inputs

$$
y=\sum_{i=1}^{5} h_{i}\left(l_{i}\right)
$$



- Results : elasticity of scale measures the percent increase in output due to one percent increase in all inputs.

$$
e(x, z)=\sum_{i=1}^{5} \frac{\partial \log f\left(l_{i}\right)}{\partial \log l_{i}}
$$

1. Unrestricted Model

$$
e(x, z)=\frac{x^{\prime} \nabla f_{x}(x, z)+z^{\prime} \nabla f_{z}(x, z)}{f(x, z)}
$$

2. Restricted Model: with $f_{2}(z)$ homogeneous of degree $r$

$$
e(x, z)=\frac{x^{\prime} \nabla f_{x}(x, z)+r^{\prime} f_{2}(z)}{f(x, z)}
$$

by Euler's theorem
3. Parametric Cobb-Douglas

$$
e(x, z)=\sum_{i=1}^{5} \beta_{i}
$$



- Scale Elasticities for Livestock Production in Wisconsin Farms

| (Full | Sample) | (Excl. | Outliers) |
| :--- | :--- | :--- | :--- |
| Mean | Med. | Mean | Med |
| 1.067 | 1.018 | 1.060 | 1.016 |
| 0.994 | 1.011 | 1.011 | 1.012 |
| 0.965 | (fixed) |  |  |

1. $\widehat{e}\left(x_{i}, z_{i}\right)$ fluctuates around 1
2. closeness of average or median scale elasticity between two models
$\Longrightarrow$ indirect evidence for the validity of restriction
3. $\hat{e}\left(x_{i}, z_{i}\right)$ 's from the restricted model are more centered around 1 than those from the unrestricted, while they are fixed as $\sum_{i=1}^{5} \widehat{\beta}_{i}=0.965$ under Cobb-Douglas.


## Conclusion

- Nonparametric Estimation of Additive Models with Homogeneous Components nonparametric : flexibilty additivity : reduction in Dimension homogeneity : economic restriction
- Asymptotic Theory of Two-Step Estimators:

> local linear fit $:$ marginal integration step
properties :asymptotic normality, optimal convergence rate





